
Microphone Techniques for Stereo and Multichannel

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What we'll look at

- How microphones behave
 - Monitoring environment
 - What different microphone configurations do for you
-
- If something doesn't make sense, stop me and ask at any time!

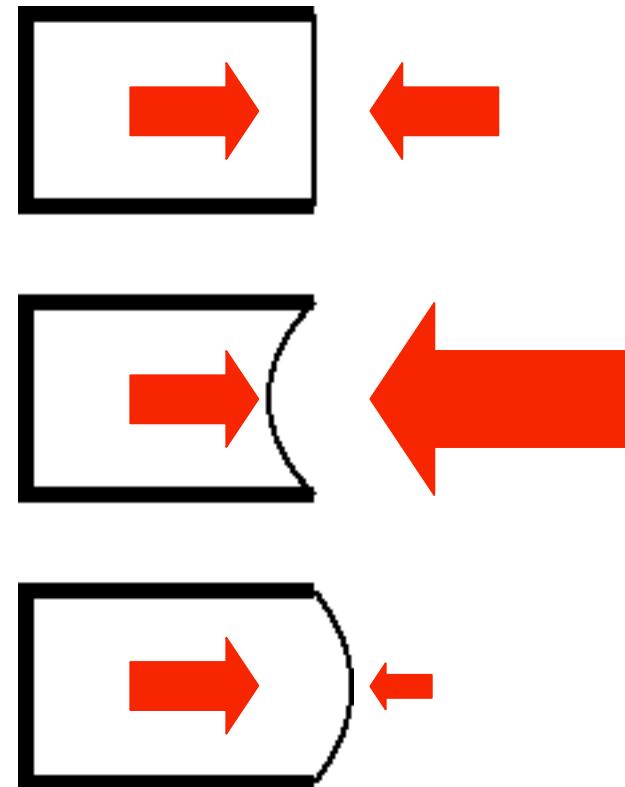
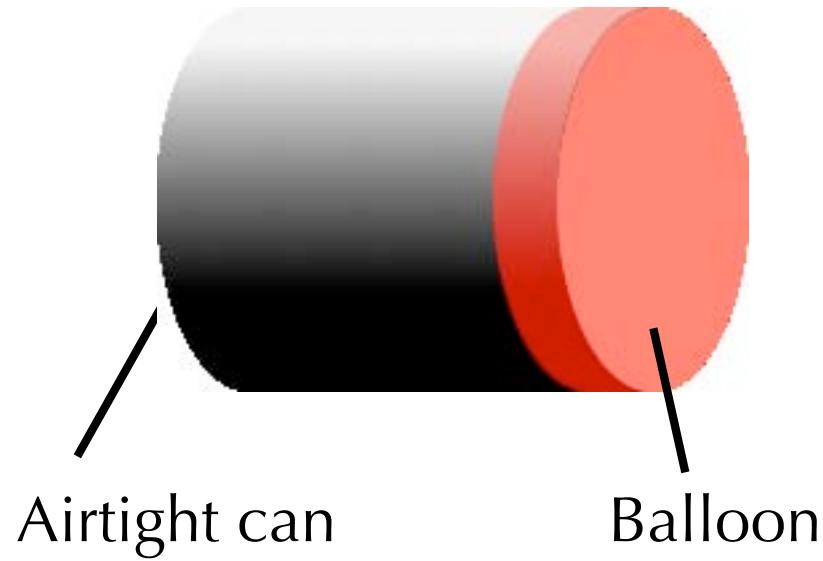


What is sound?

- Today's barometric pressure is about 100 kPa
- Sound is a change in that pressure over time
- A microphone converts that pressure change into a voltage change

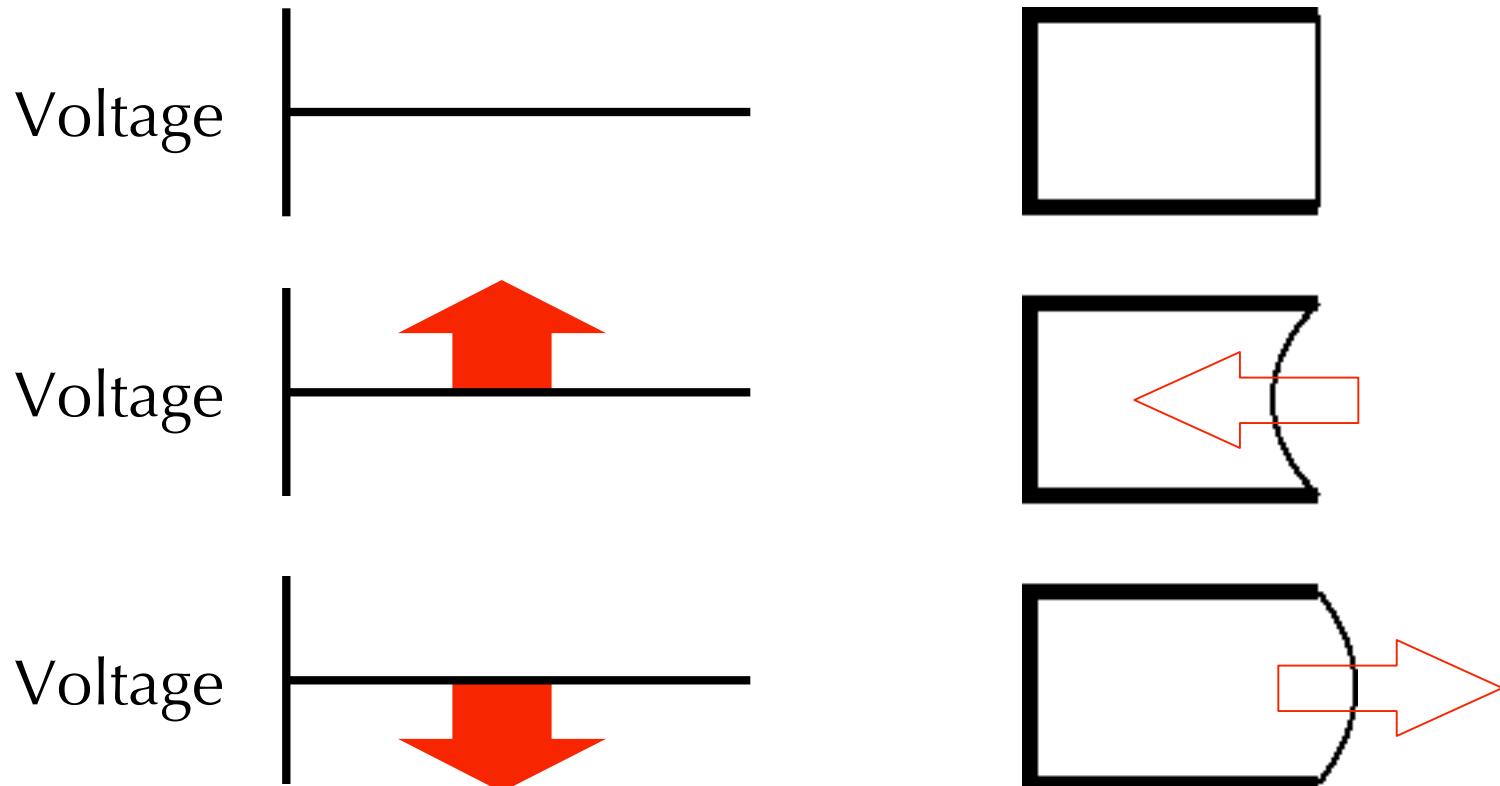


How to make a barometer

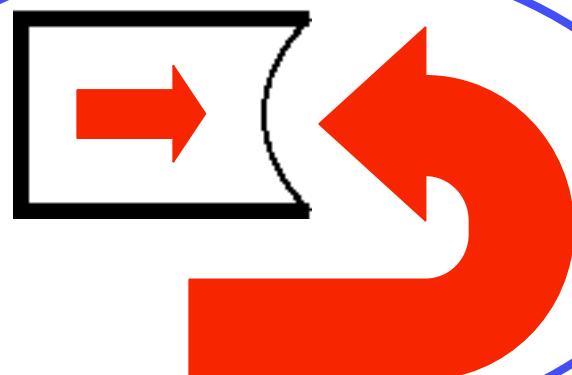
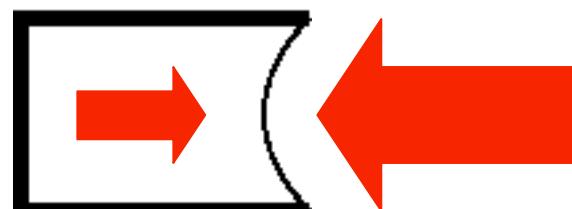
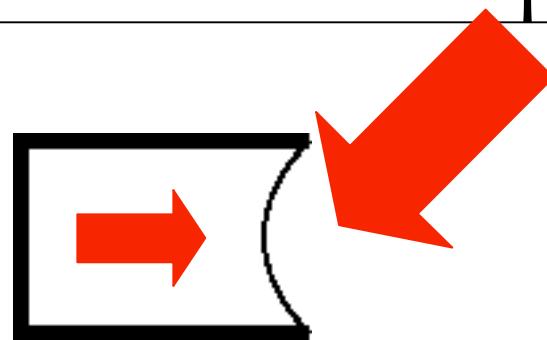


How to make a ~~barometer~~

pressure microphone



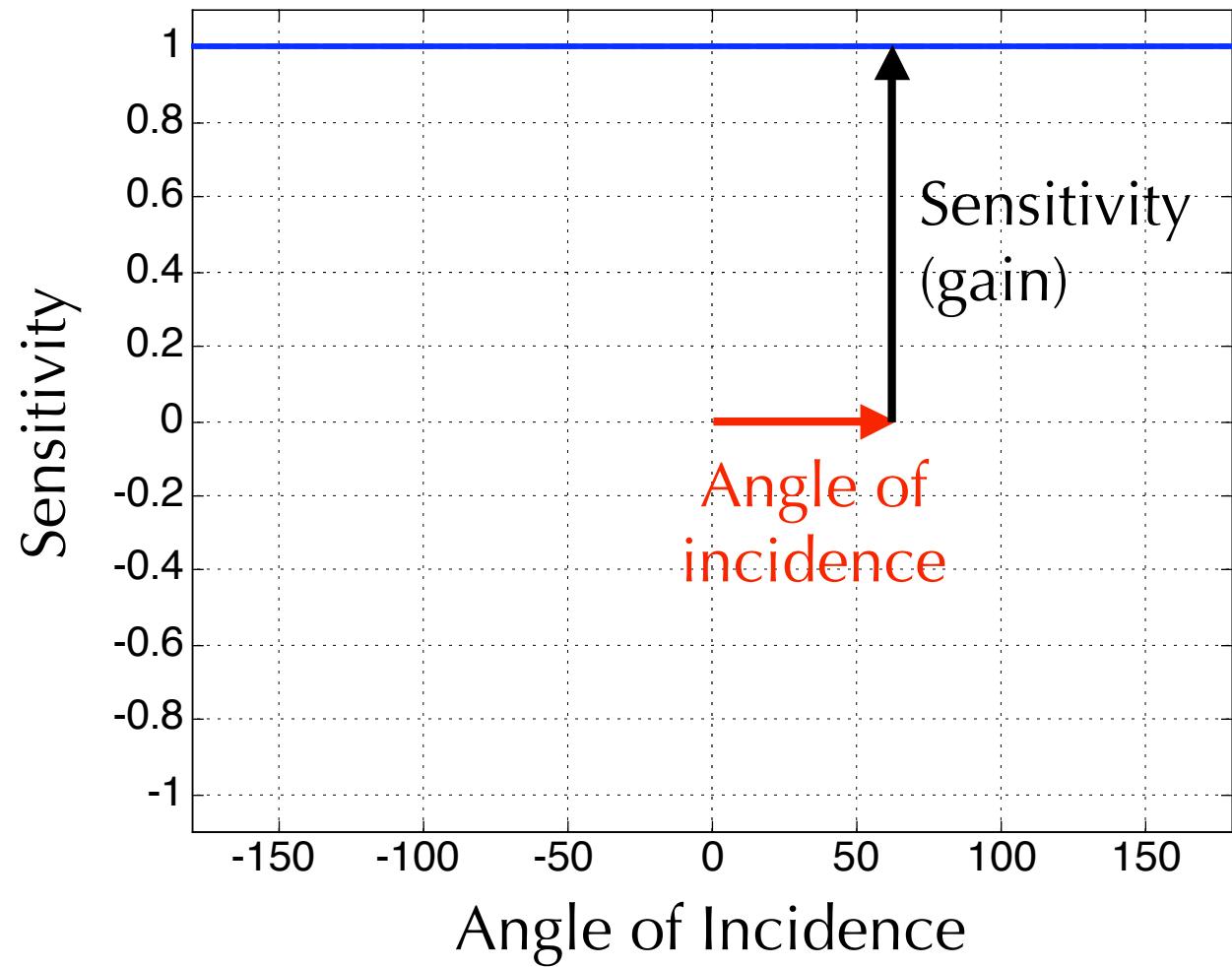
How to make a pressure microphone



B&O

Pressure Microphone - Sensitivity

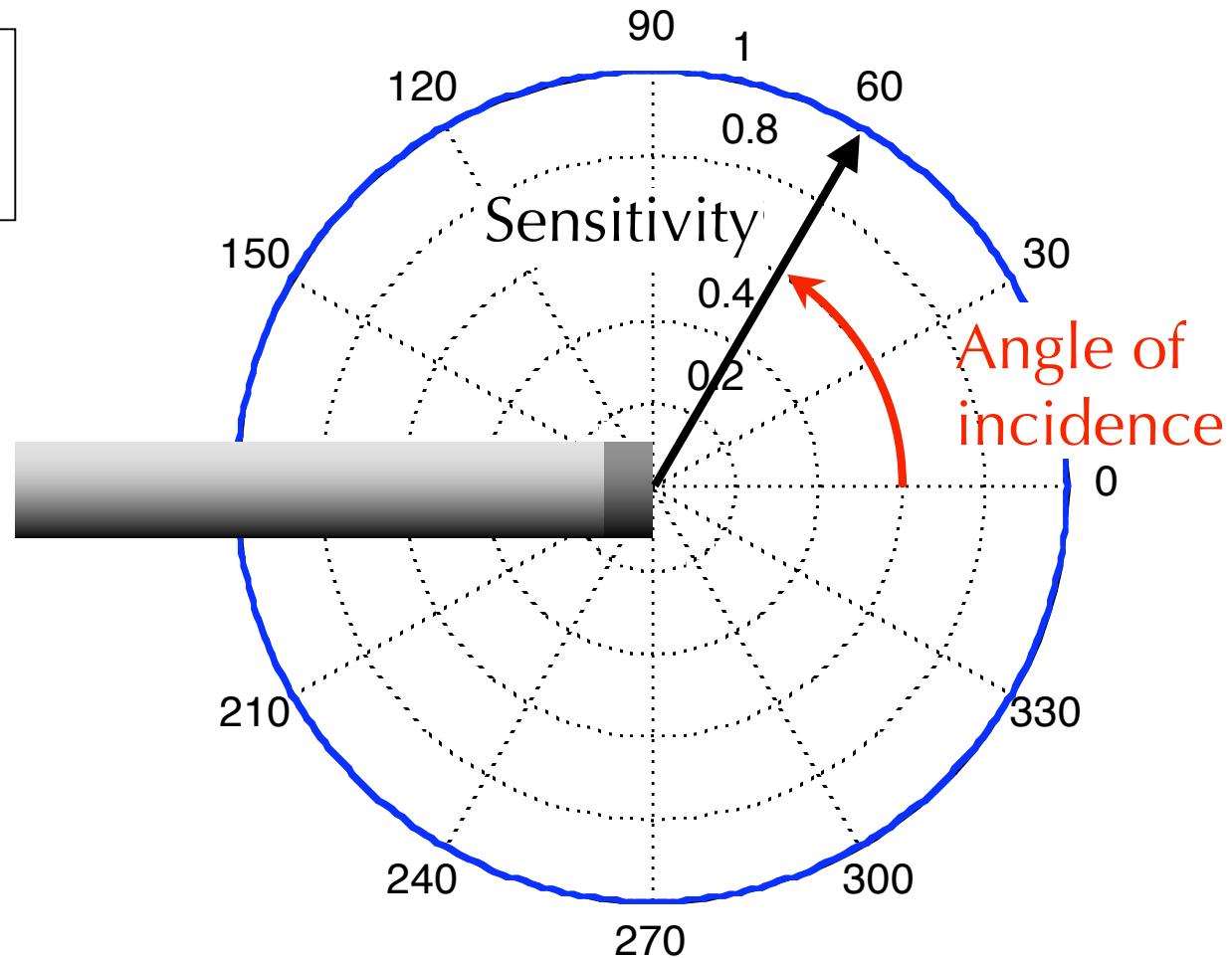
$$S = 1$$



Omnidirectional

~~Pressure~~ microphone - Sensitivity

$$S = 1$$



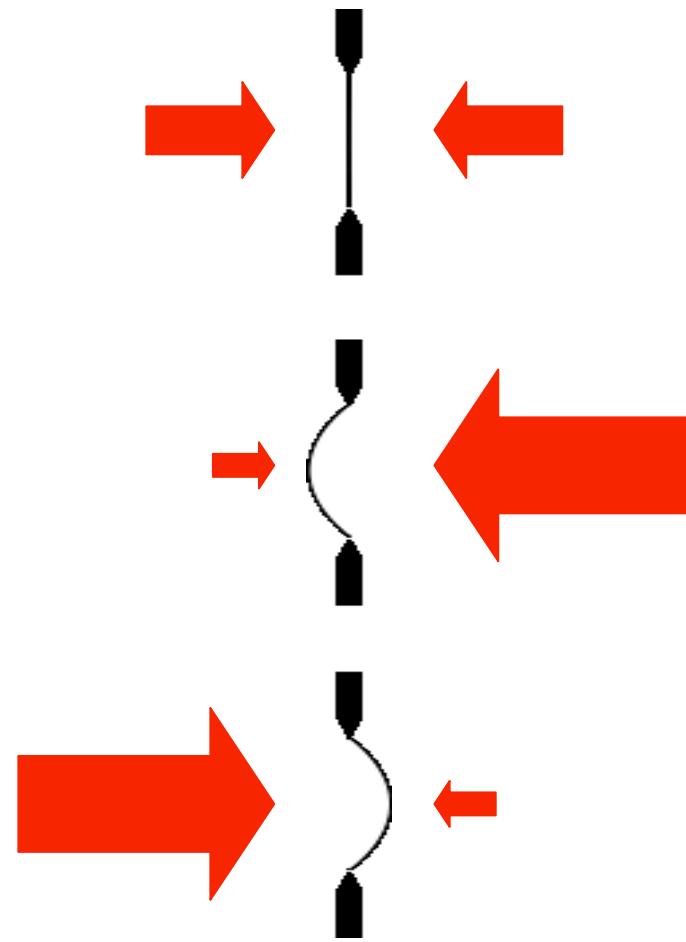
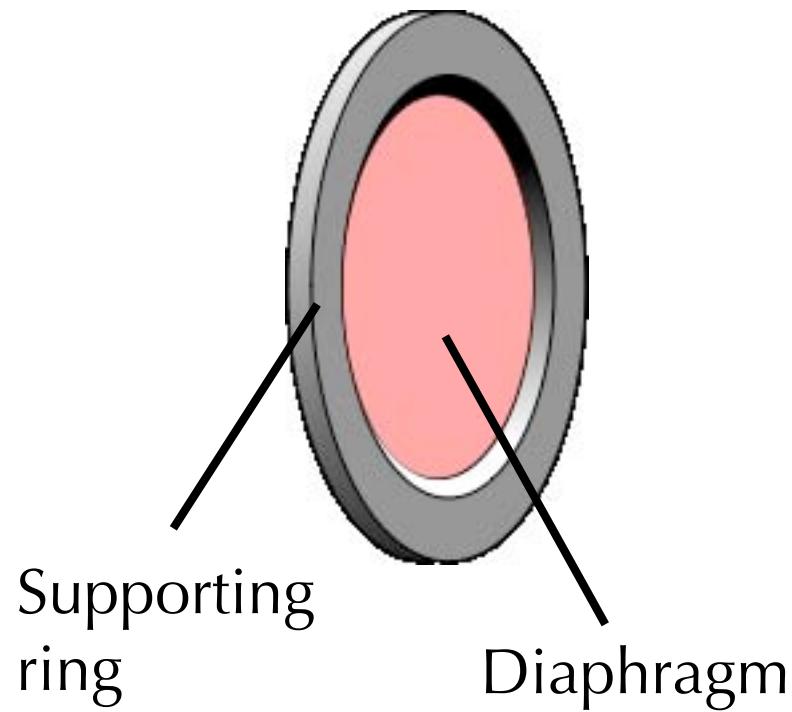
B&O

Let's start again...

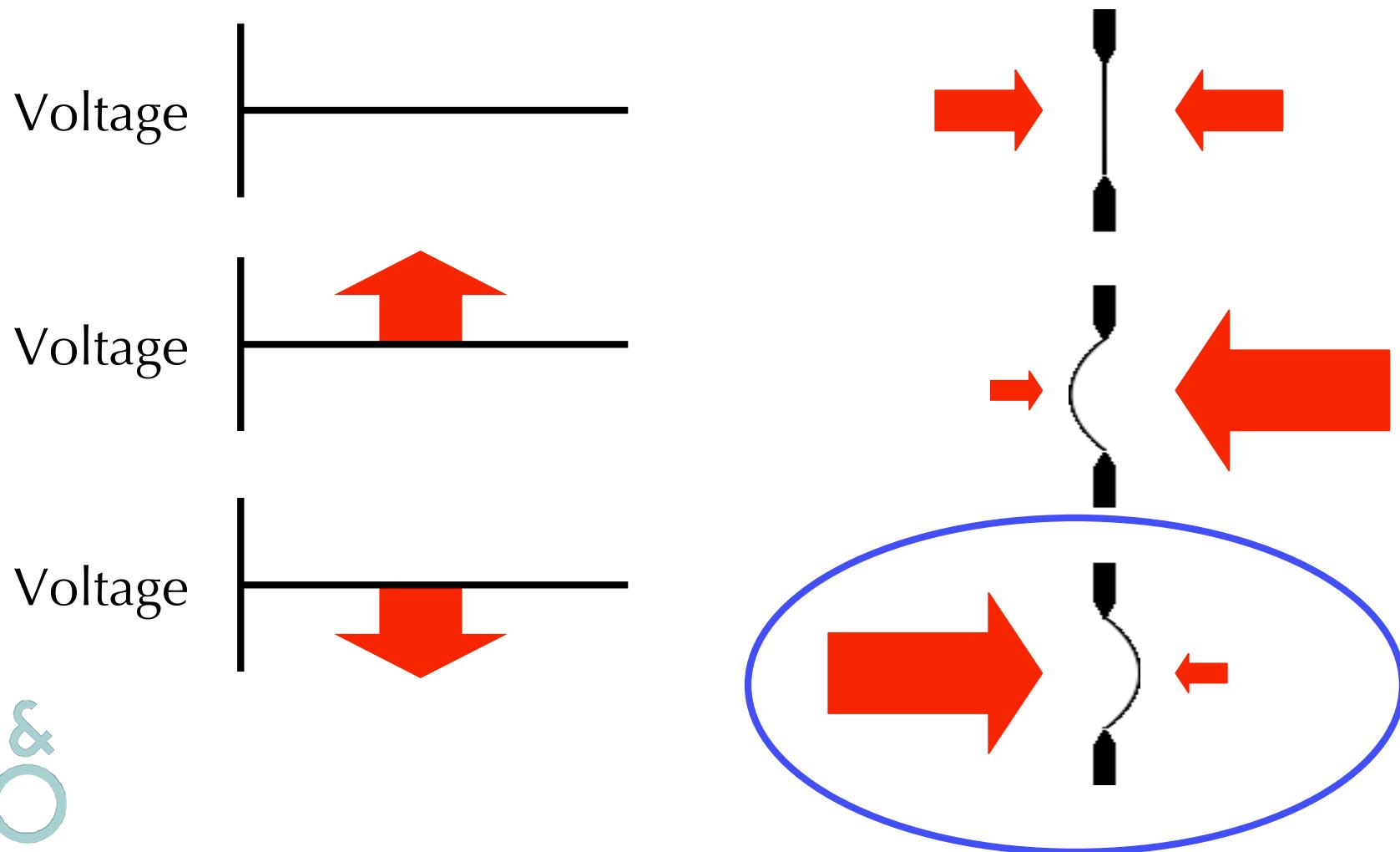
- We'll build another “barometer” but this time without the sealed can
- This means we are measuring the *difference* in pressure on the front and back of the diaphragm
- Pressure Difference = Pressure Gradient



Pressure Gradient microphone - Construction

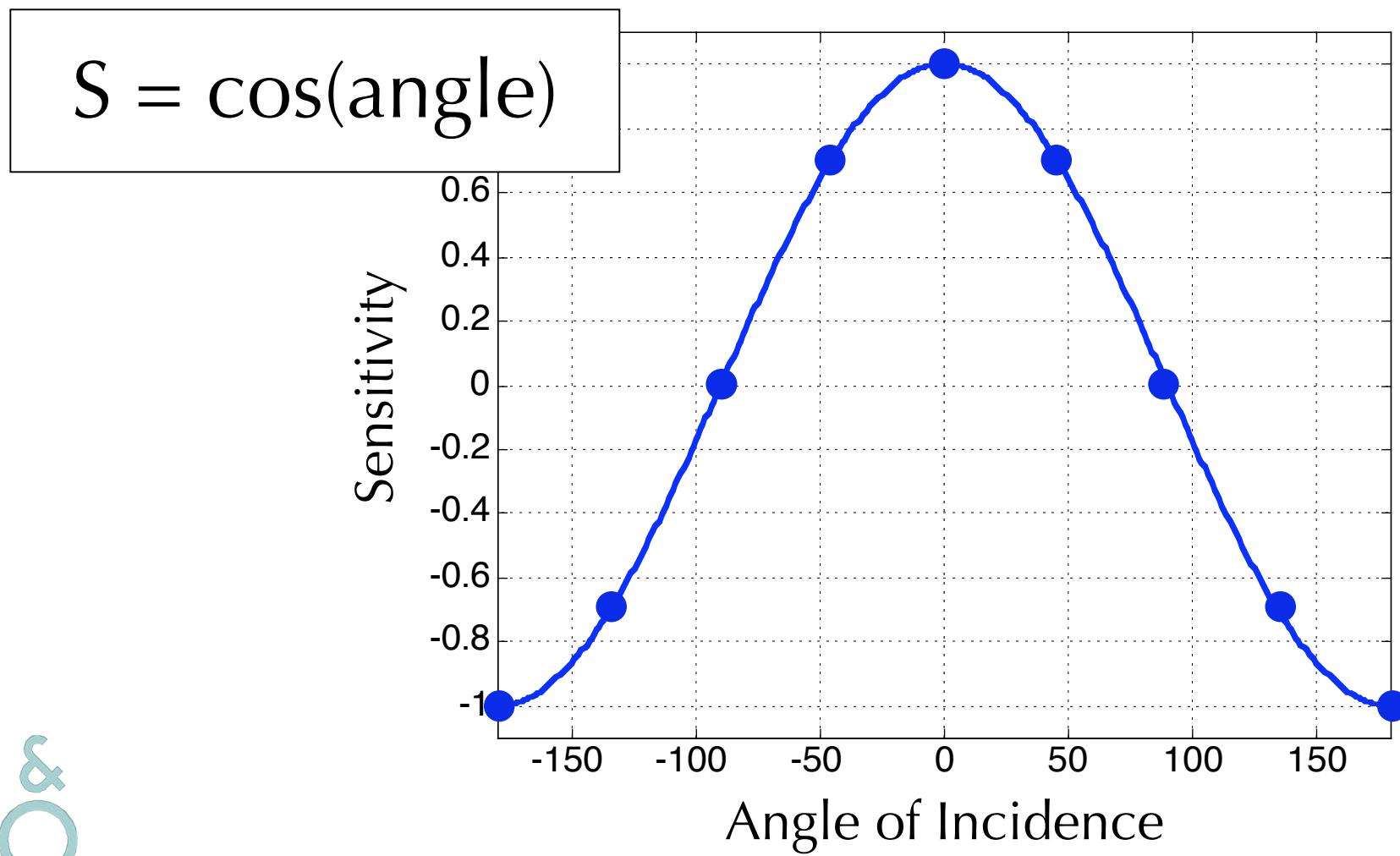


Pressure Gradient microphone - Output



B&O

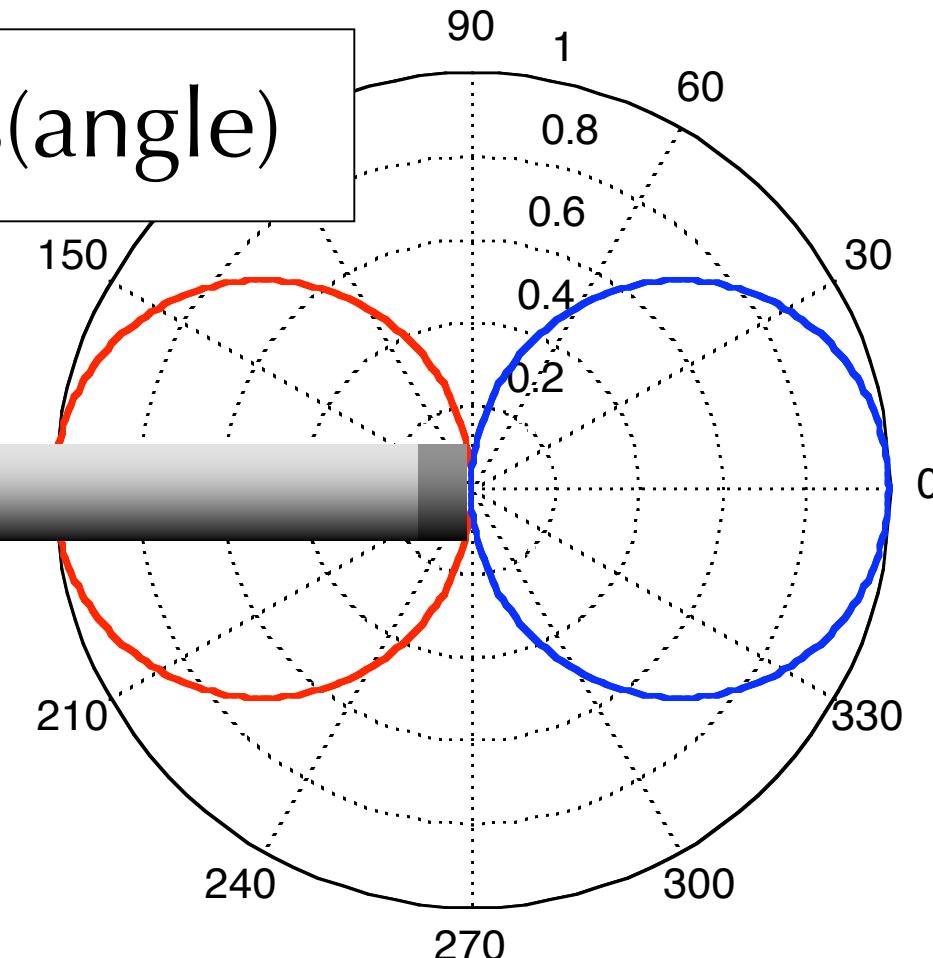
Pressure Gradient microphone - Sensitivity



Bidirectional

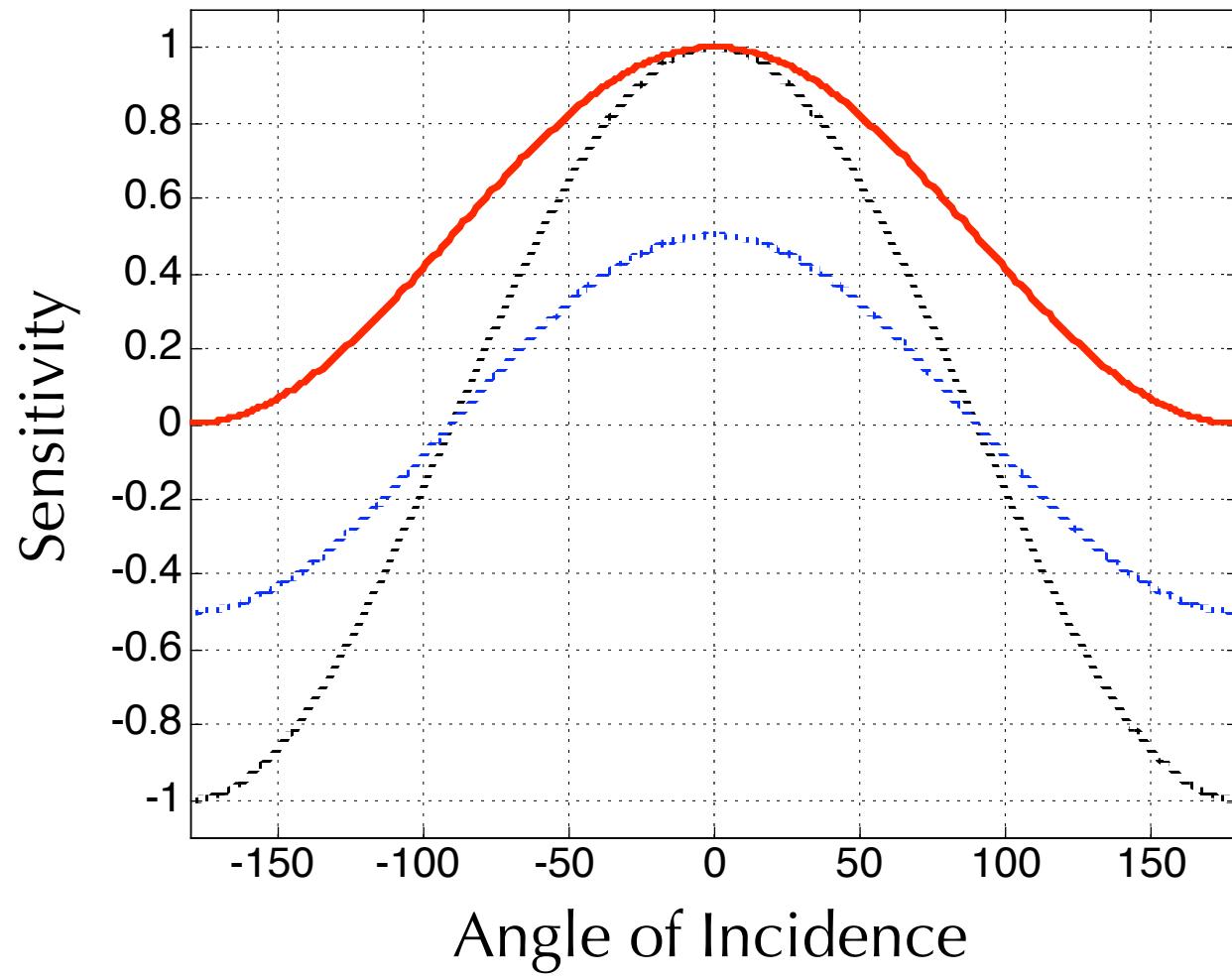
~~Pressure Gradient~~ microphone - Sensitivity

$$S = \cos(\text{angle})$$

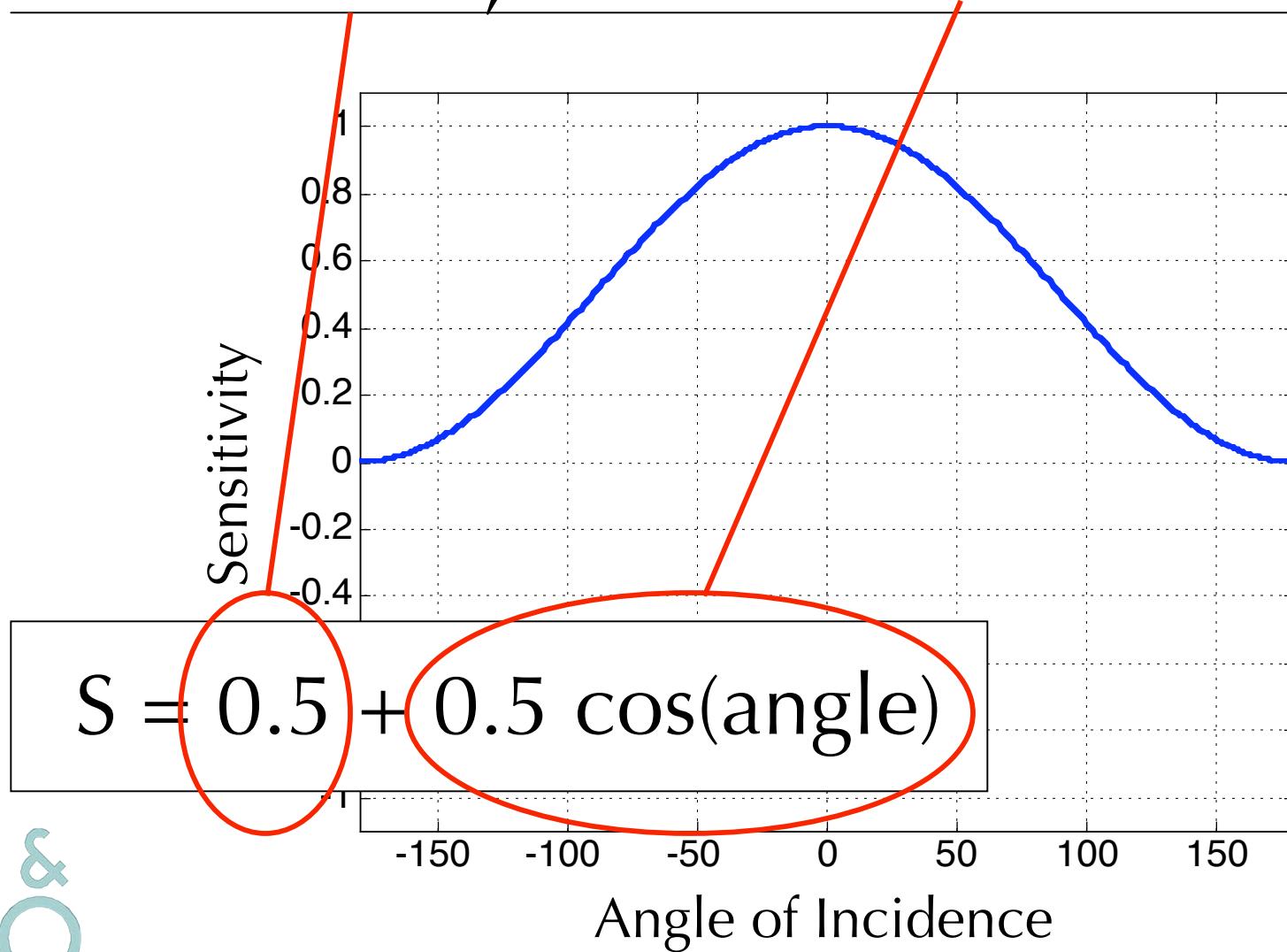


B&O

Let's add them...

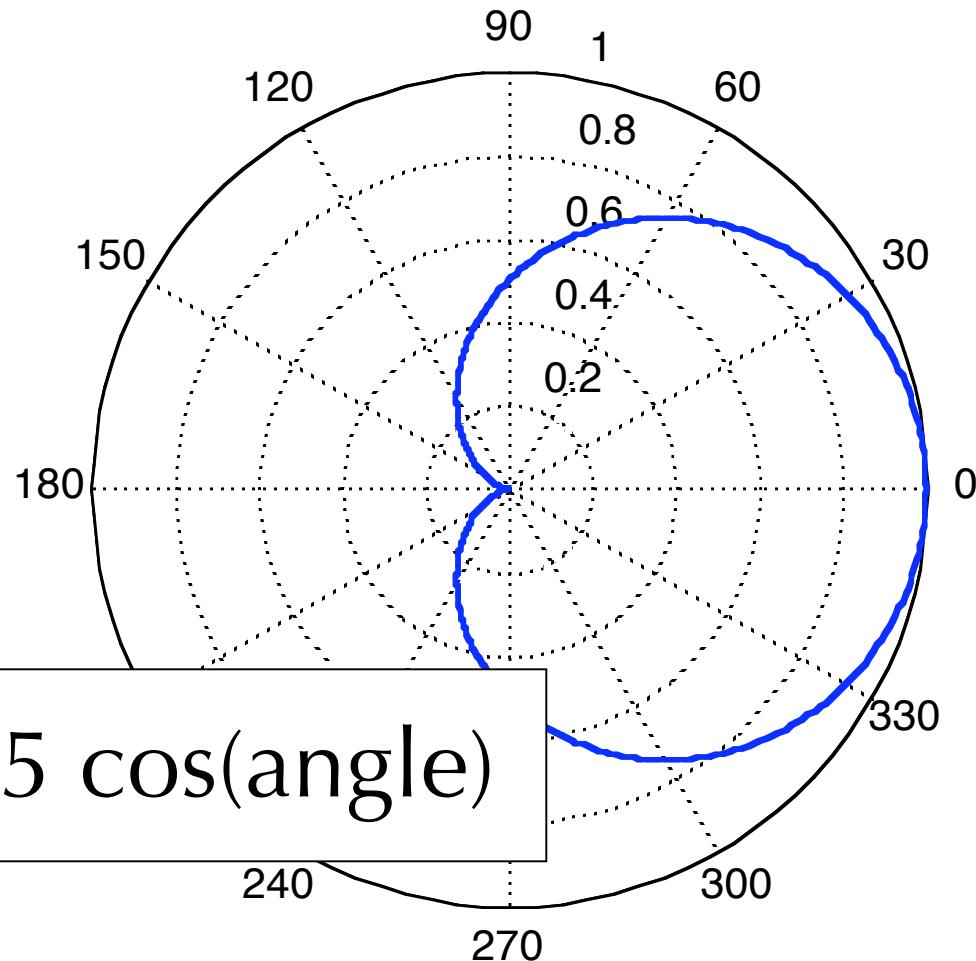


Half-omni, half-bidirectional



Cardioid microphone

~~Half-omni, half-bidirectional~~



Make your own Polar Patterns

| | Pressure (Omnidirectional) | Pressure Gradient (Bidirectional) |
|------------------------|---------------------------------------|--|
| Omnidirectional | 100% | 0% |
| Subcardioid | 75% | 25% |
| Cardioid | 50% | 50% |
| Hypercardioid | 25% | 75% |
| Bidirectional | 0% | 100% |



Polar Patterns

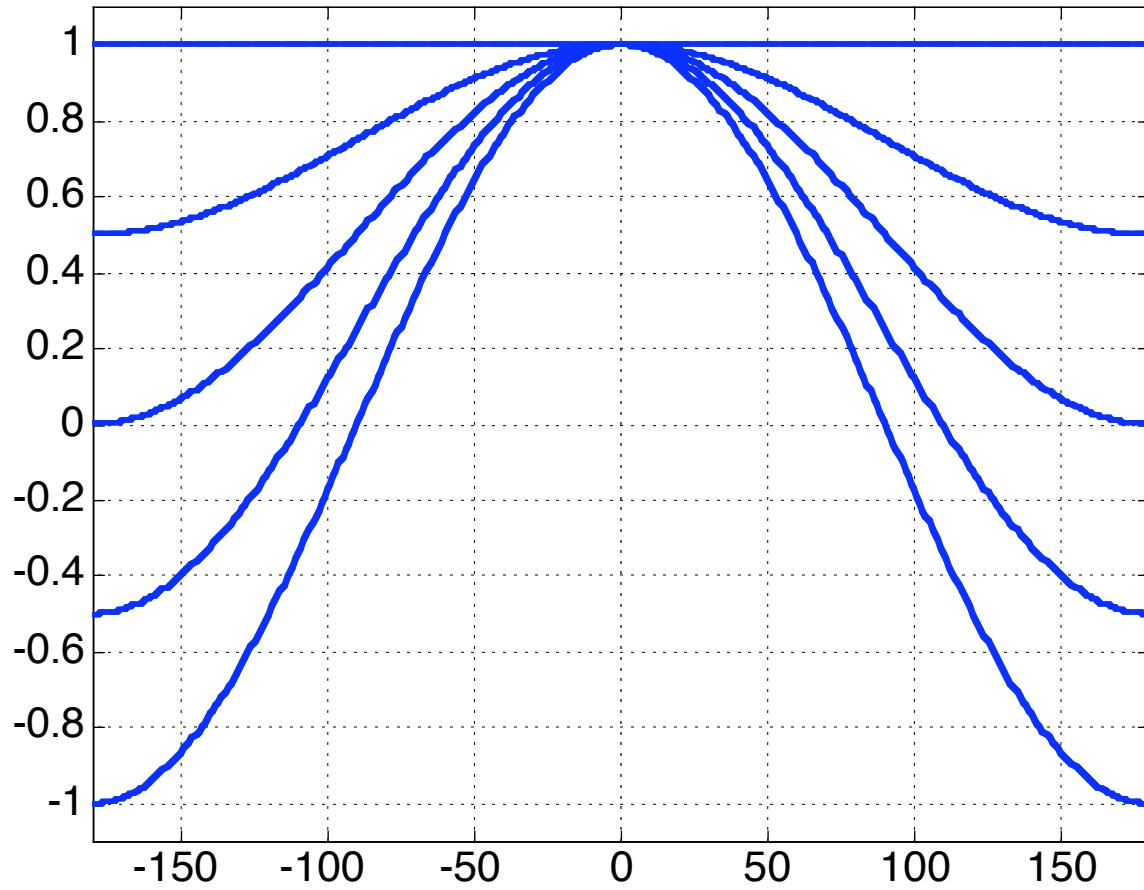
Omnidirectional

Subcardioid

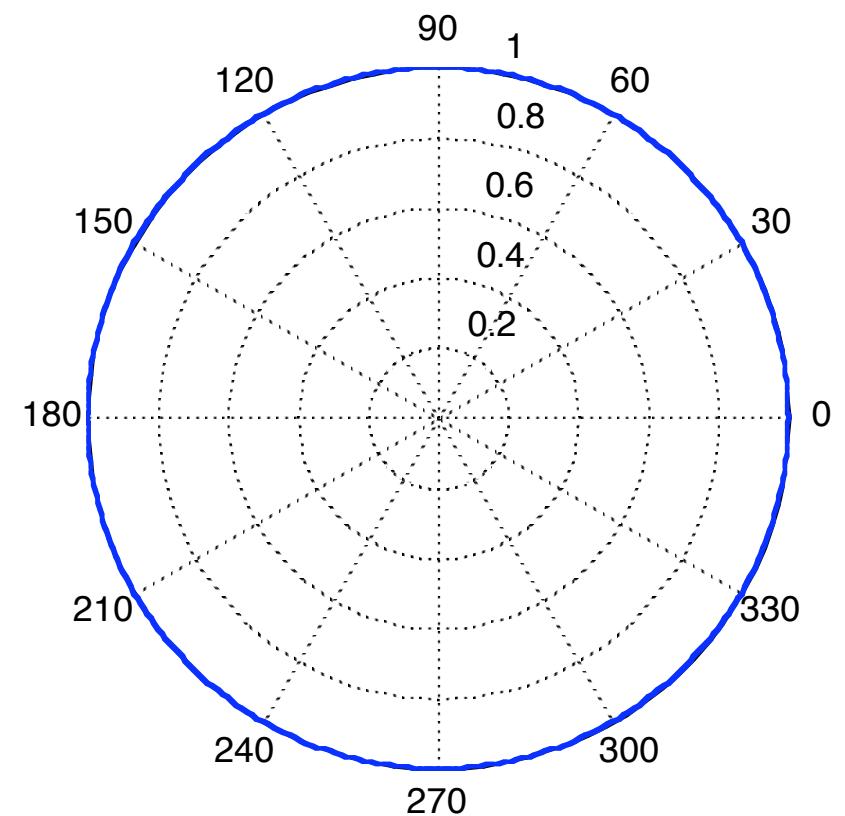
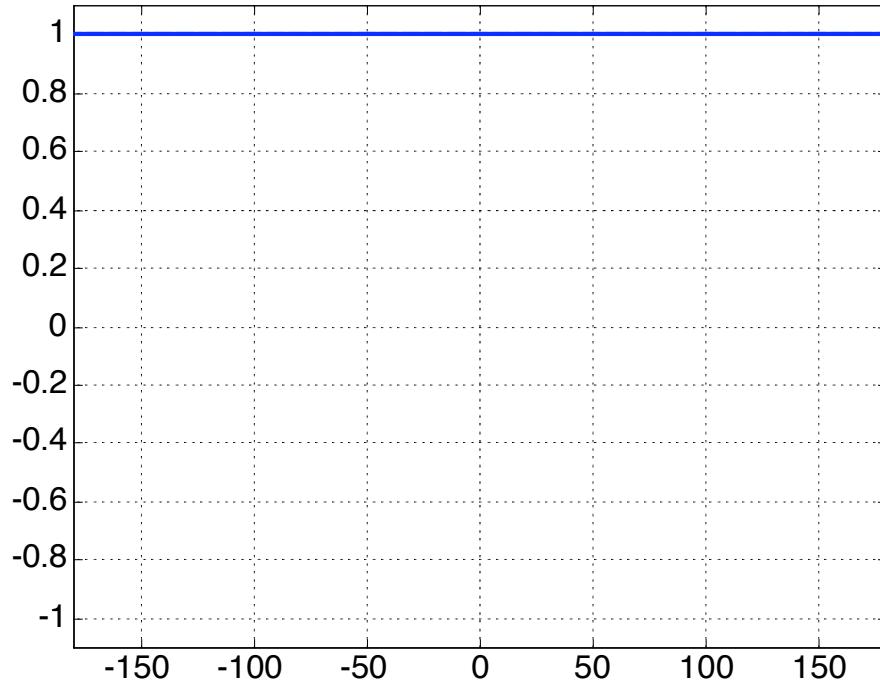
Cardioid

Hypercardioid

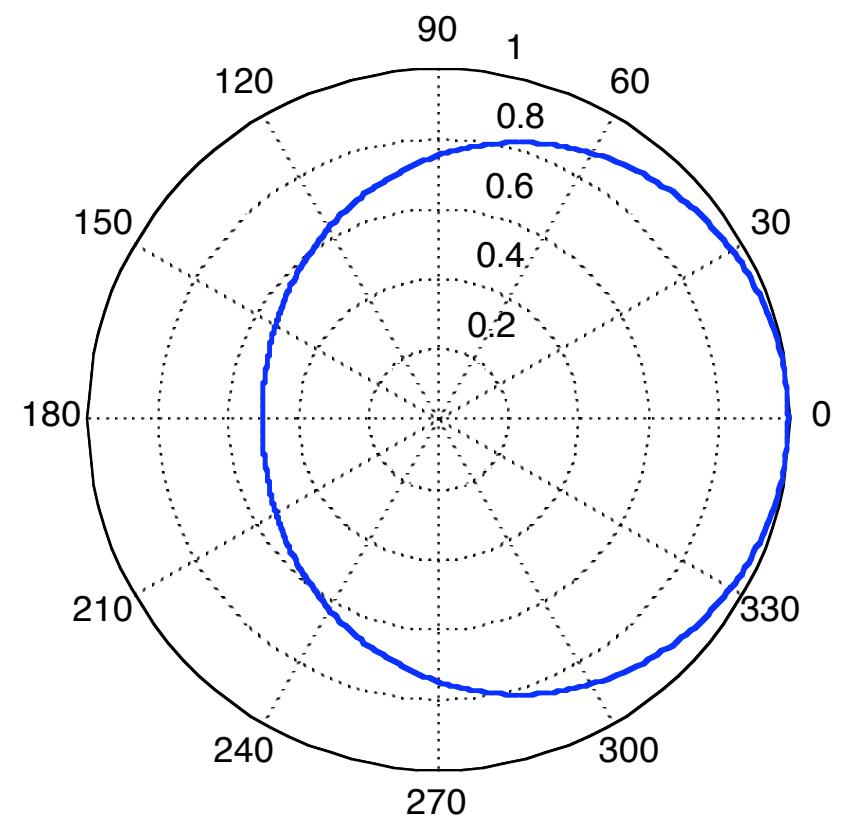
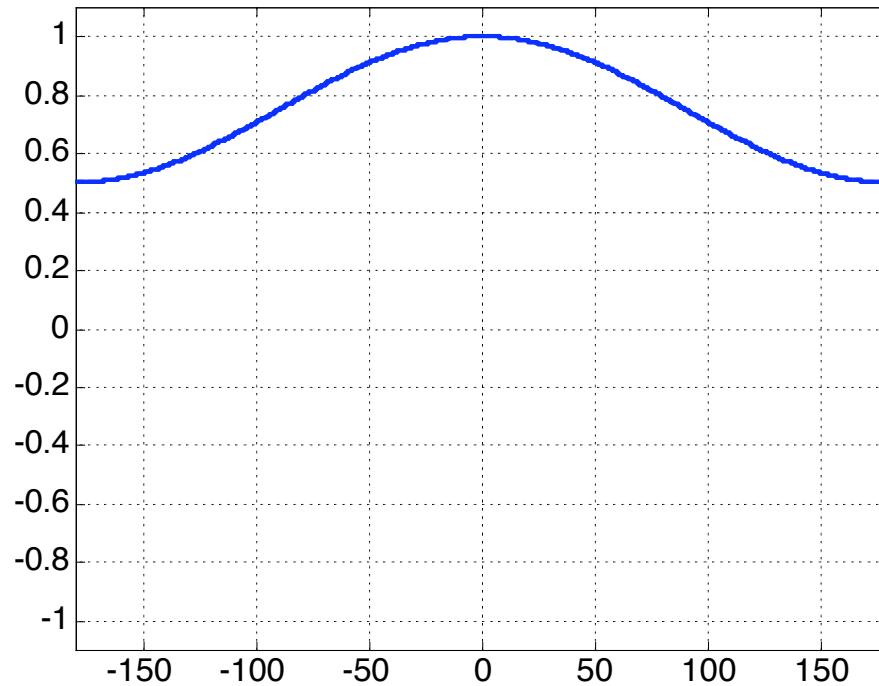
Bidirectional



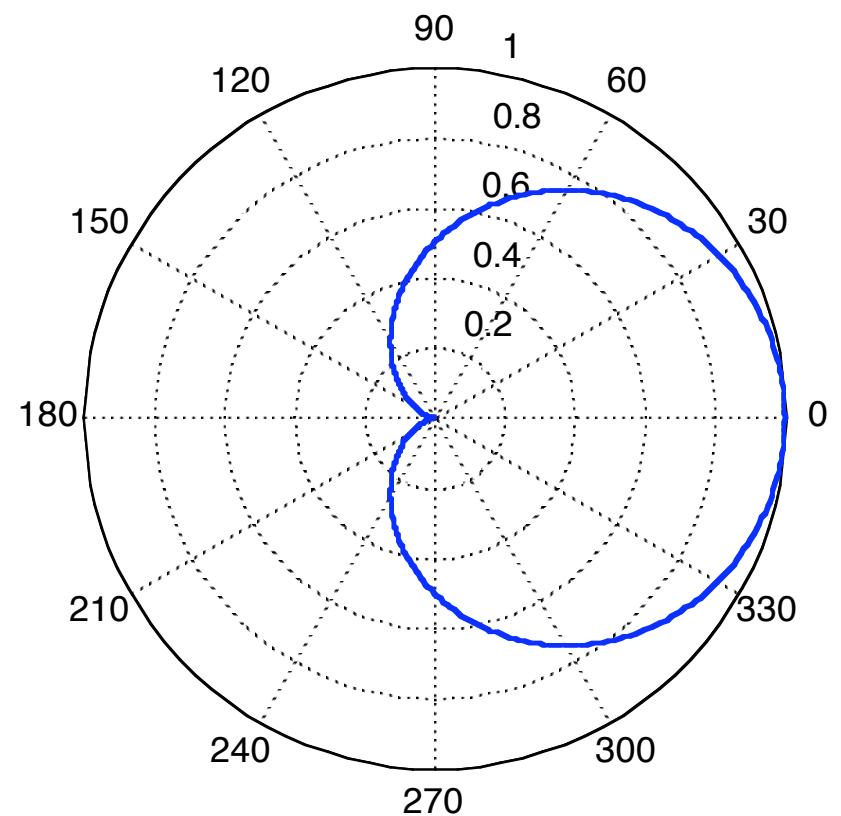
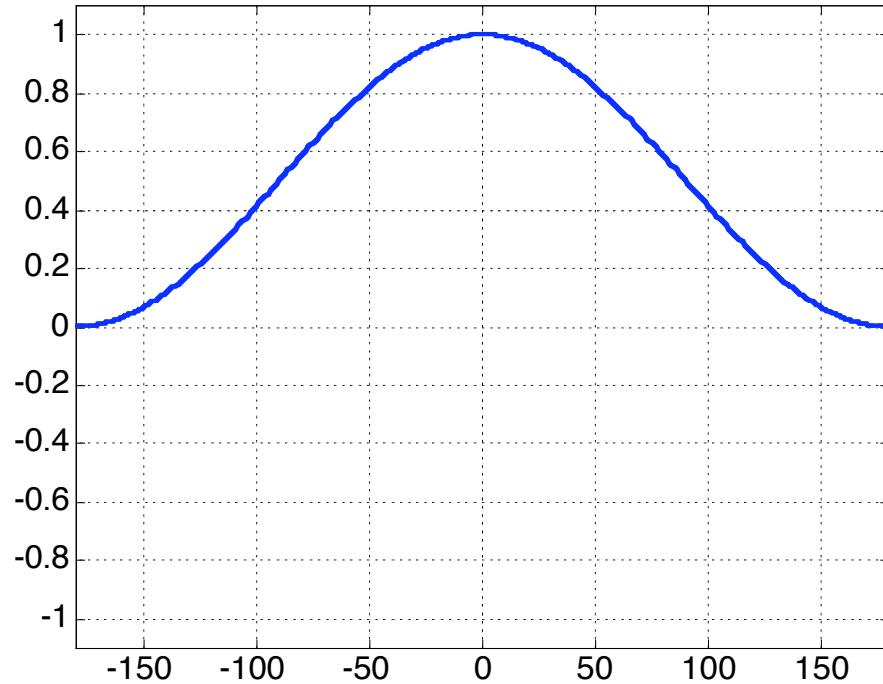
Omnidirectional



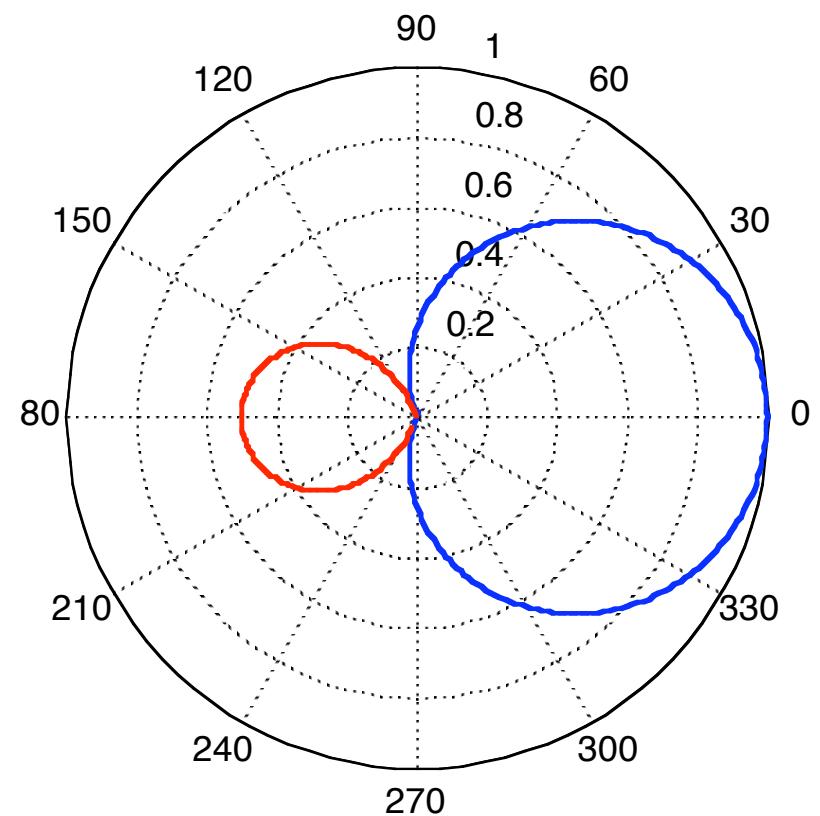
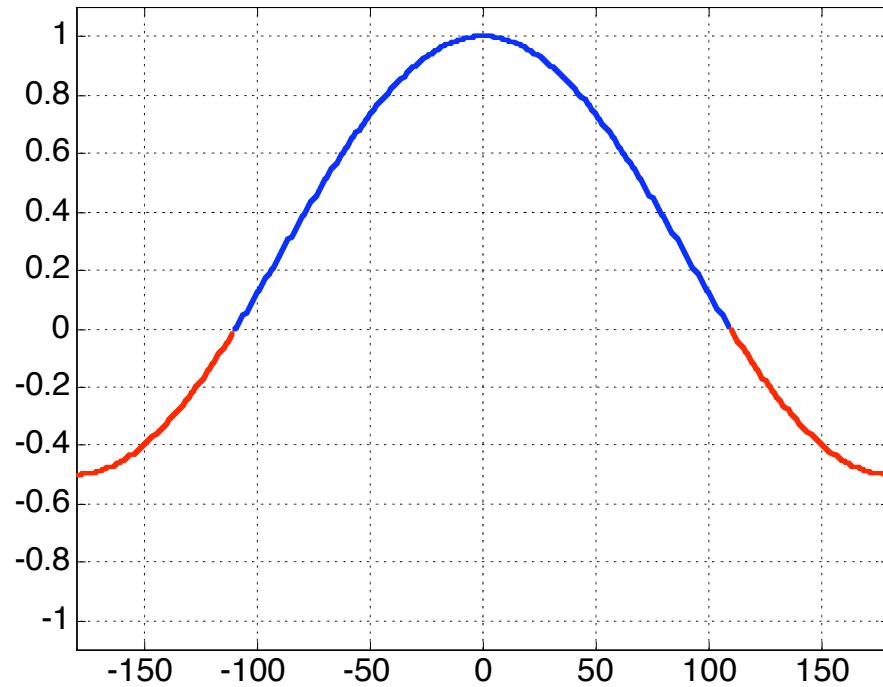
Subcardioid



Cardioid

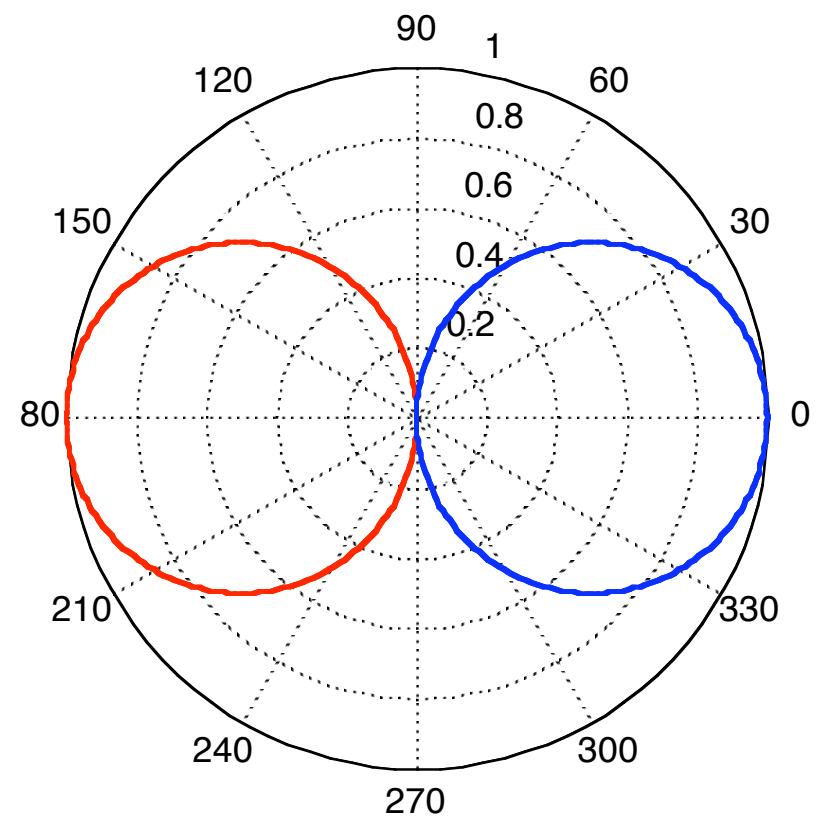
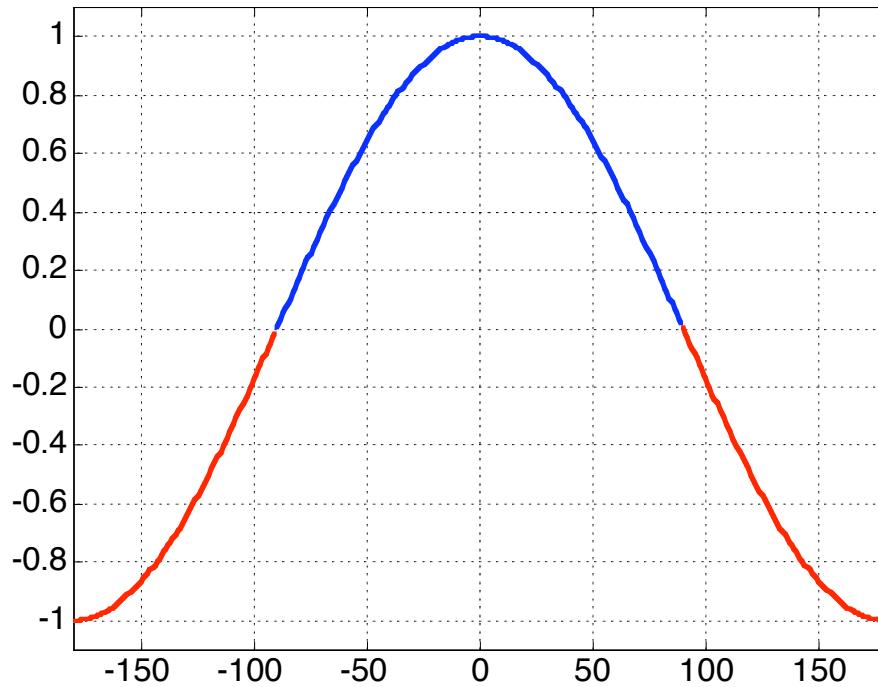


Hypercardioid



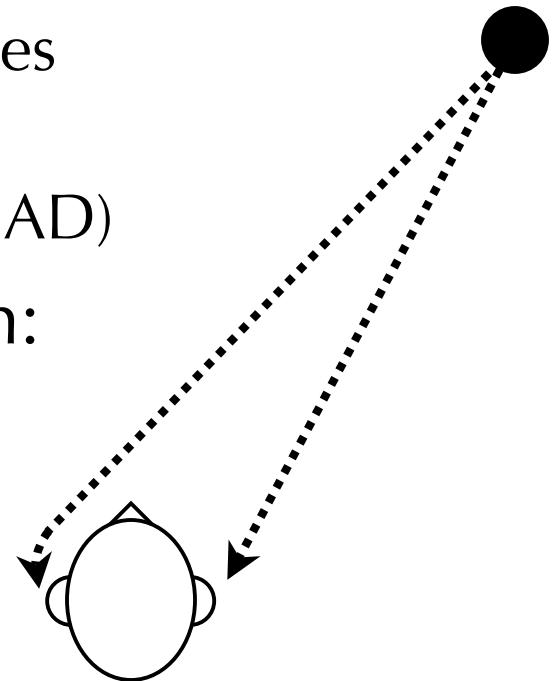
B & O

Bidirectional



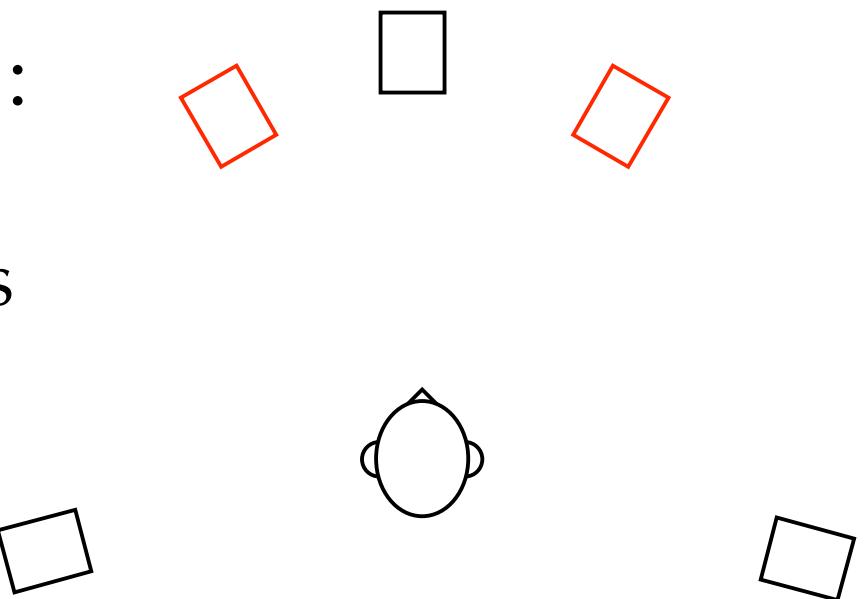
Localisation in the real world

- Left-right localisation relies on:
 - Interaural time of arrival differences (ITD)
 - Interaural amplitude differences (IAD)
- Front-back localisation relies on:
 - Head rotation cues
 - Reflections off the pinnae
 - Shoulder reflections



Localization in the reproduced world

- Phantom image localization relies on:
 - Interchannel amplitude differences
 - Interchannel time differences



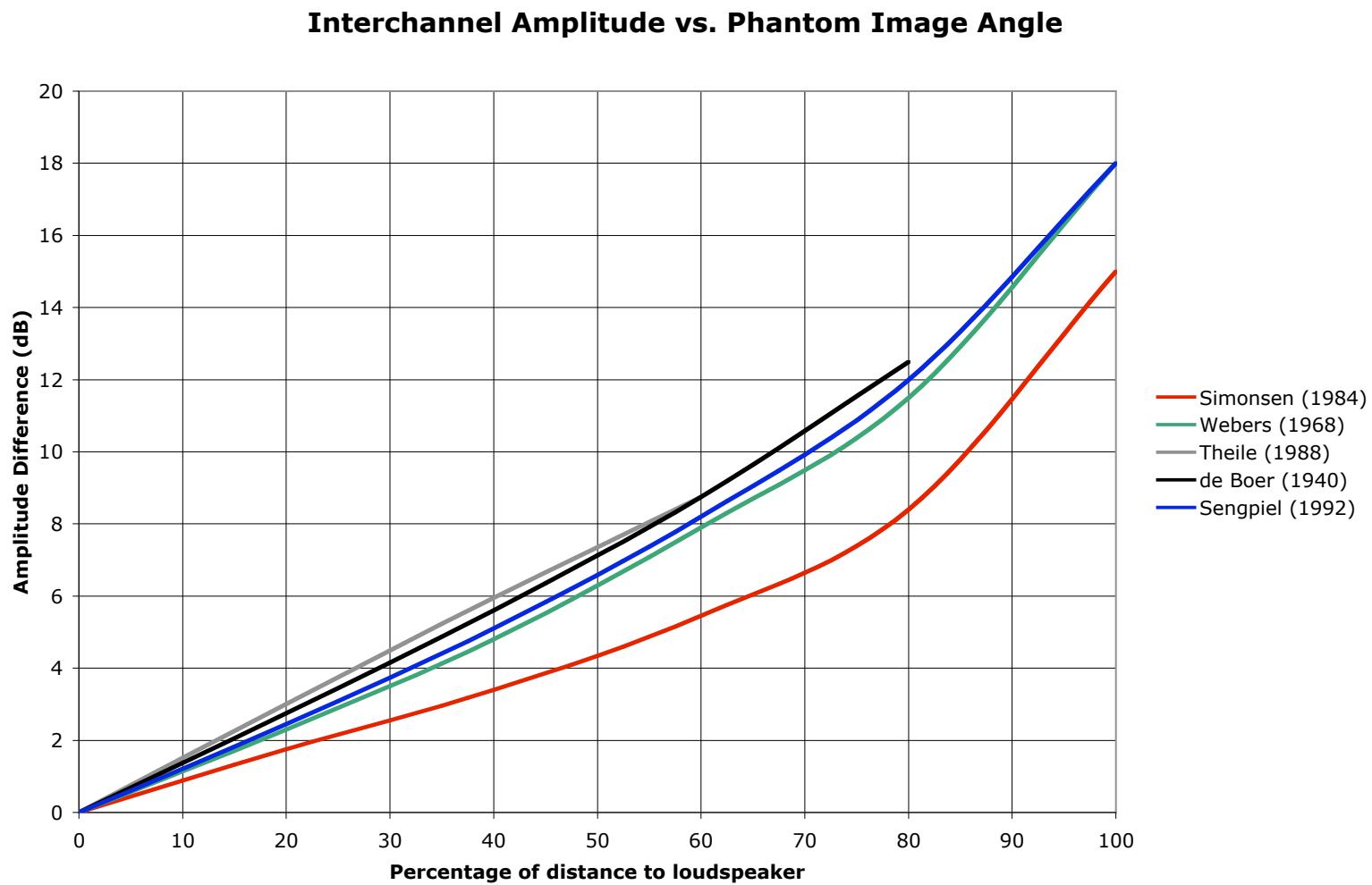
One version...

| Image position | Δ Amp. | or | Δ Time |
|-----------------------|----------------------|----|----------------------|
| 0° | 0.0 dB | or | 0.0 ms |
| 10° | 2.5 dB | or | 0.2 ms |
| 20° | 5.5 dB | or | 0.44 ms |
| 30° | 15 dB | or | 1.12 ms |

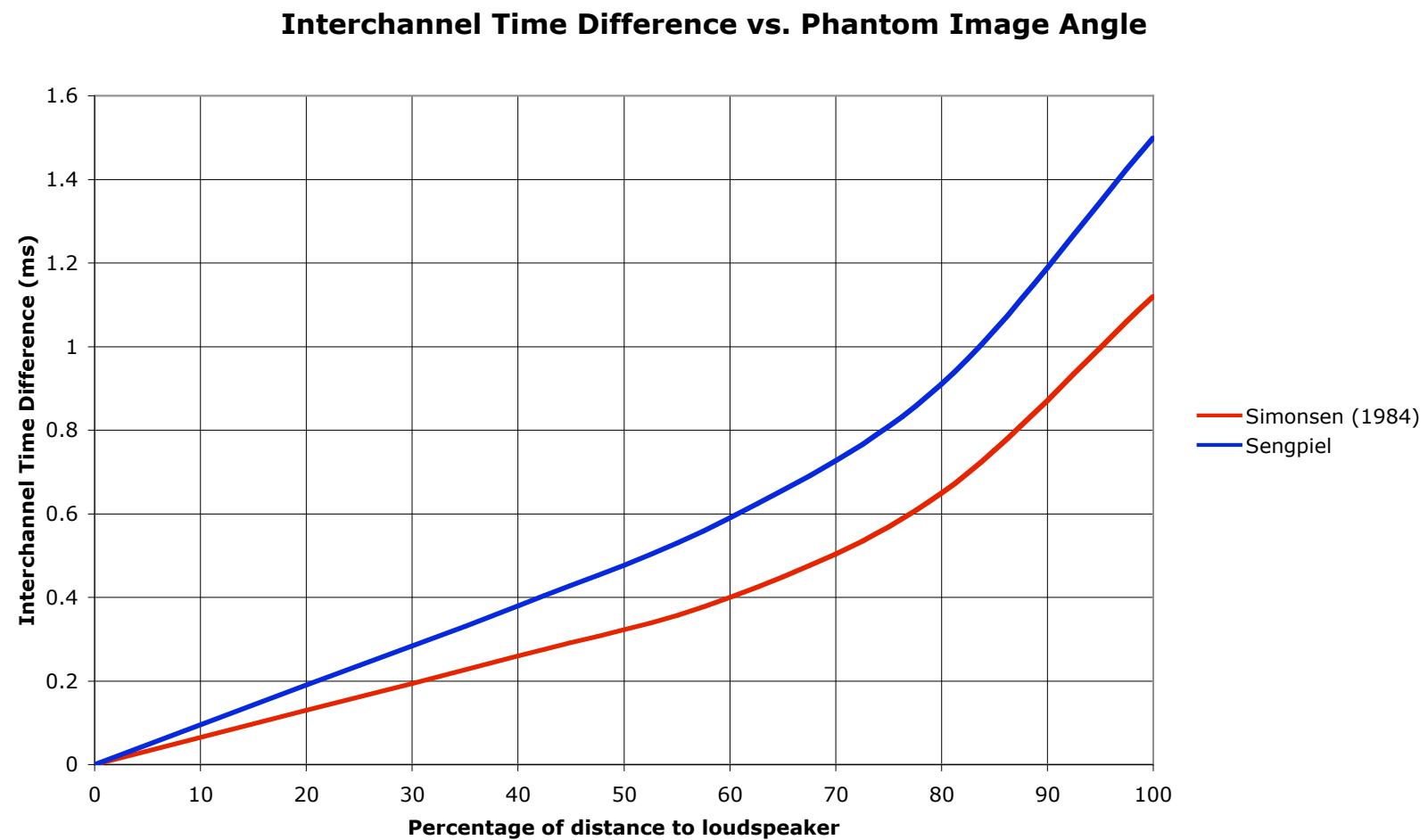


Gert Simonsen 1983

Other versions...



Other versions...

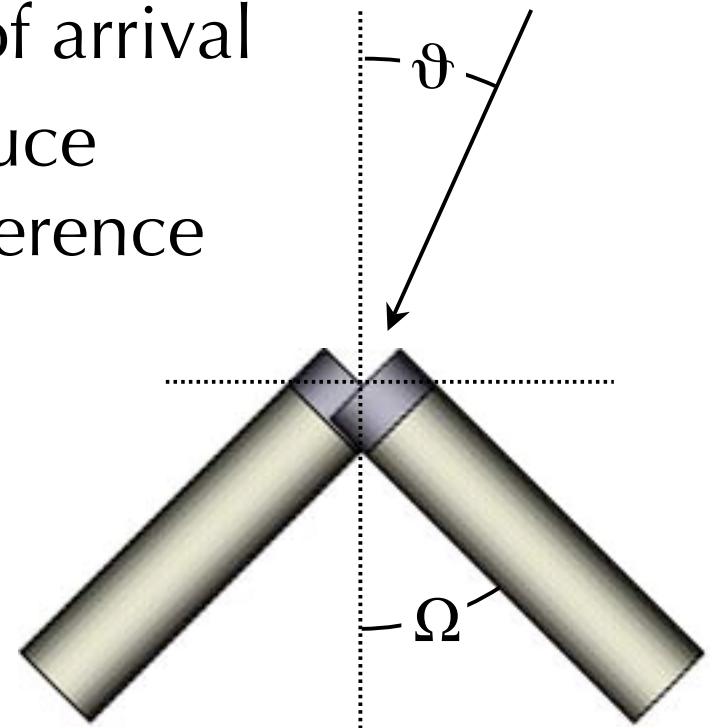


Coincident Microphones

- We assume identical time of arrival
- Sensitivity differences produce interchannel amplitude difference

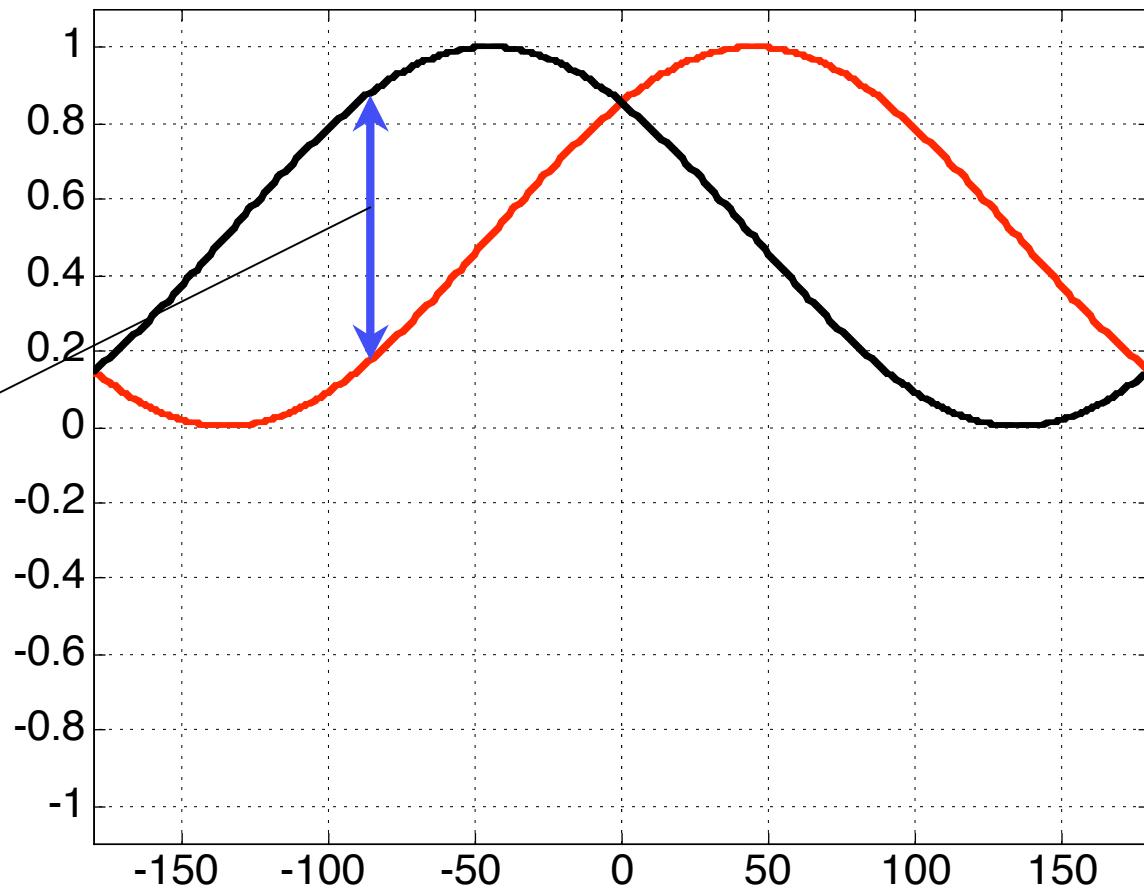
$$S_n = P_n + G_n \cos (\vartheta + \Omega_n)$$

$$DS = 20 \log_{10} \left| \frac{S_1}{S_2} \right|$$

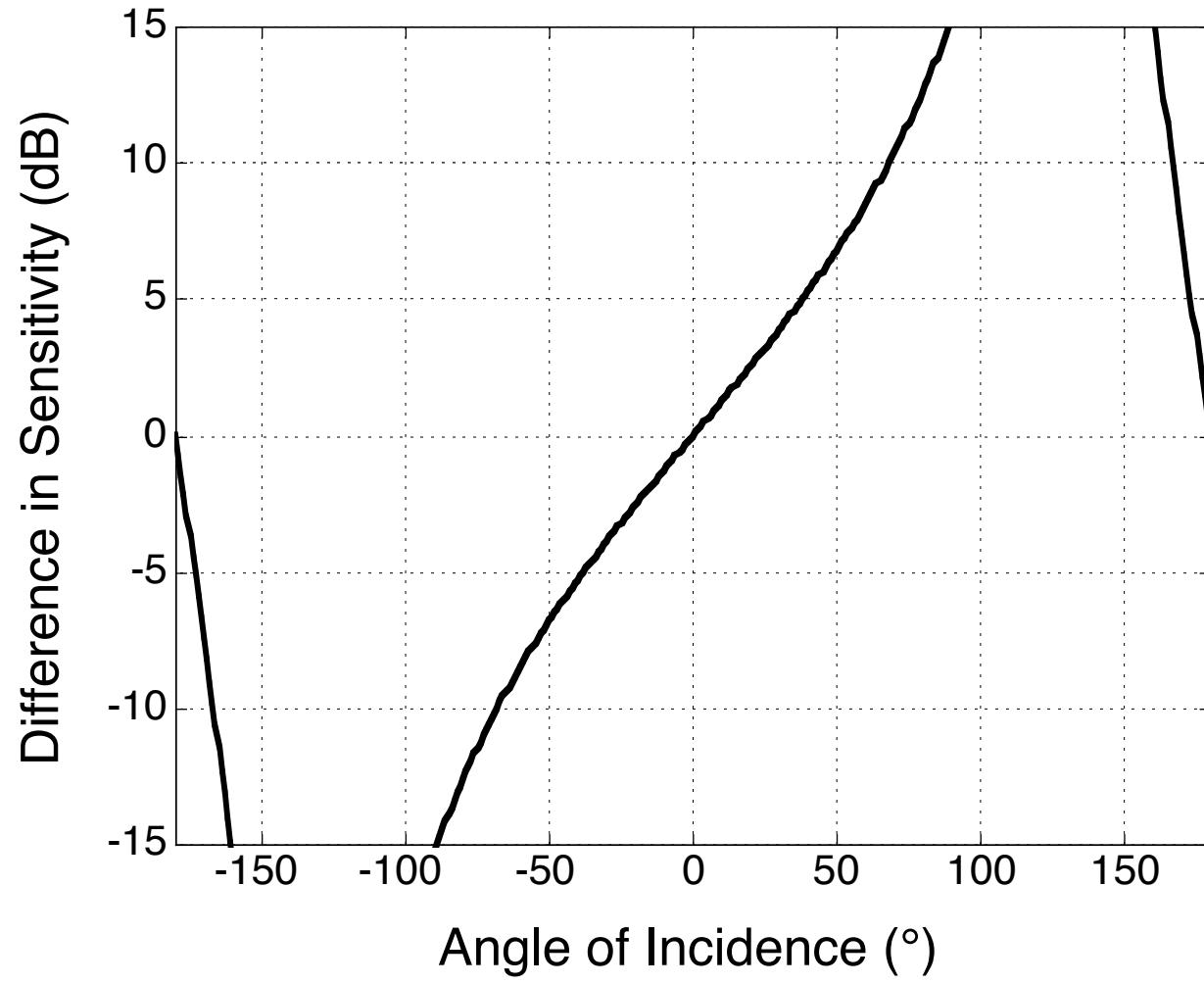


90° Cardioids - Sensitivity Difference

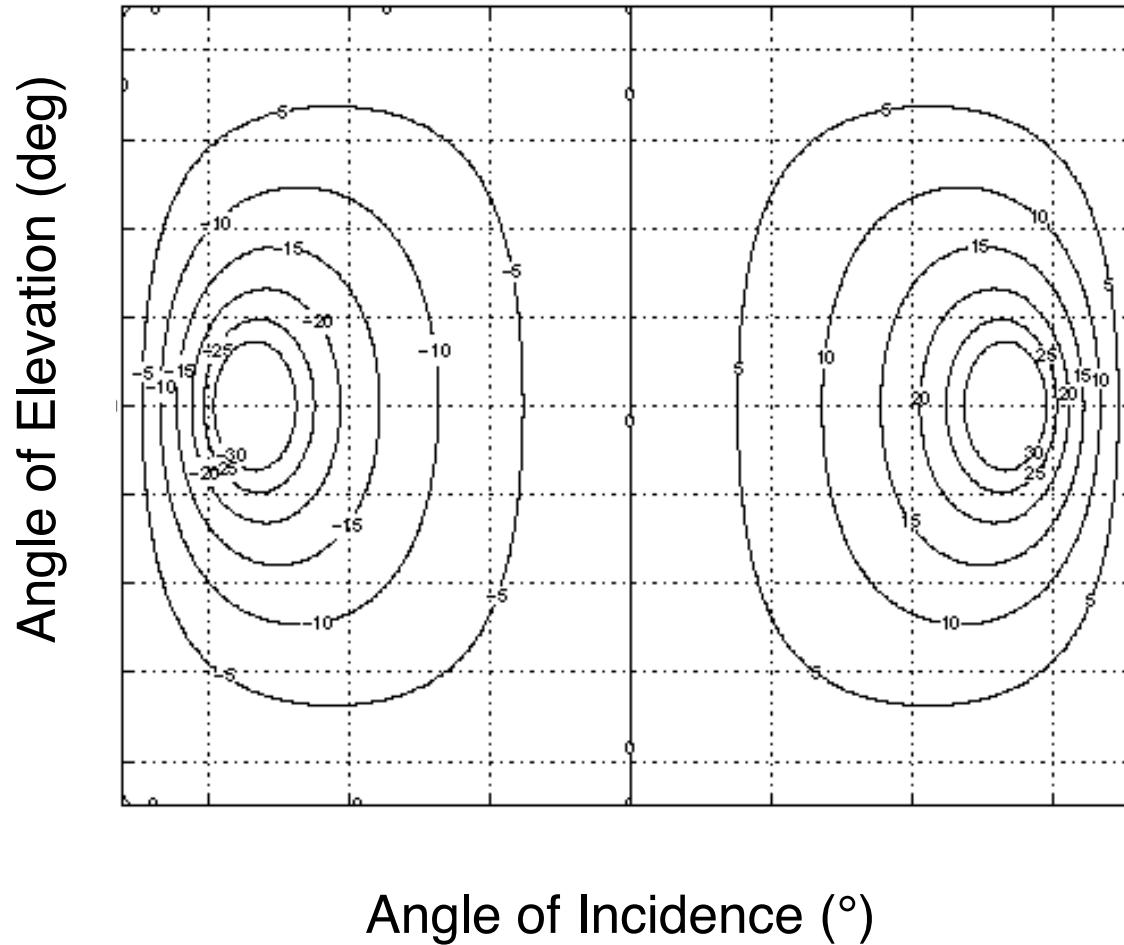
Difference in
Sensitivity



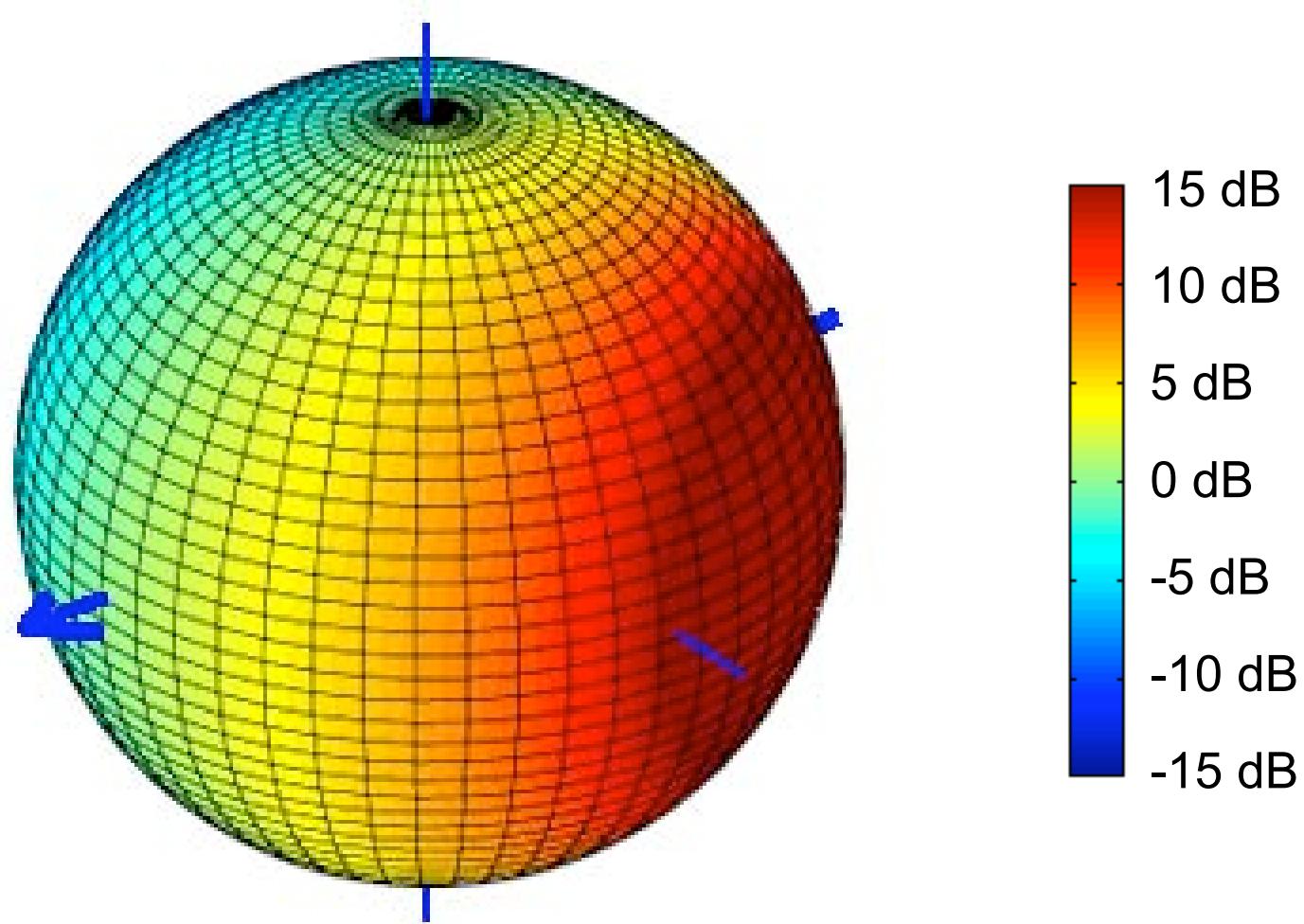
90° Cardioids - Sensitivity Difference



90° Cardioids - Sensitivity Difference



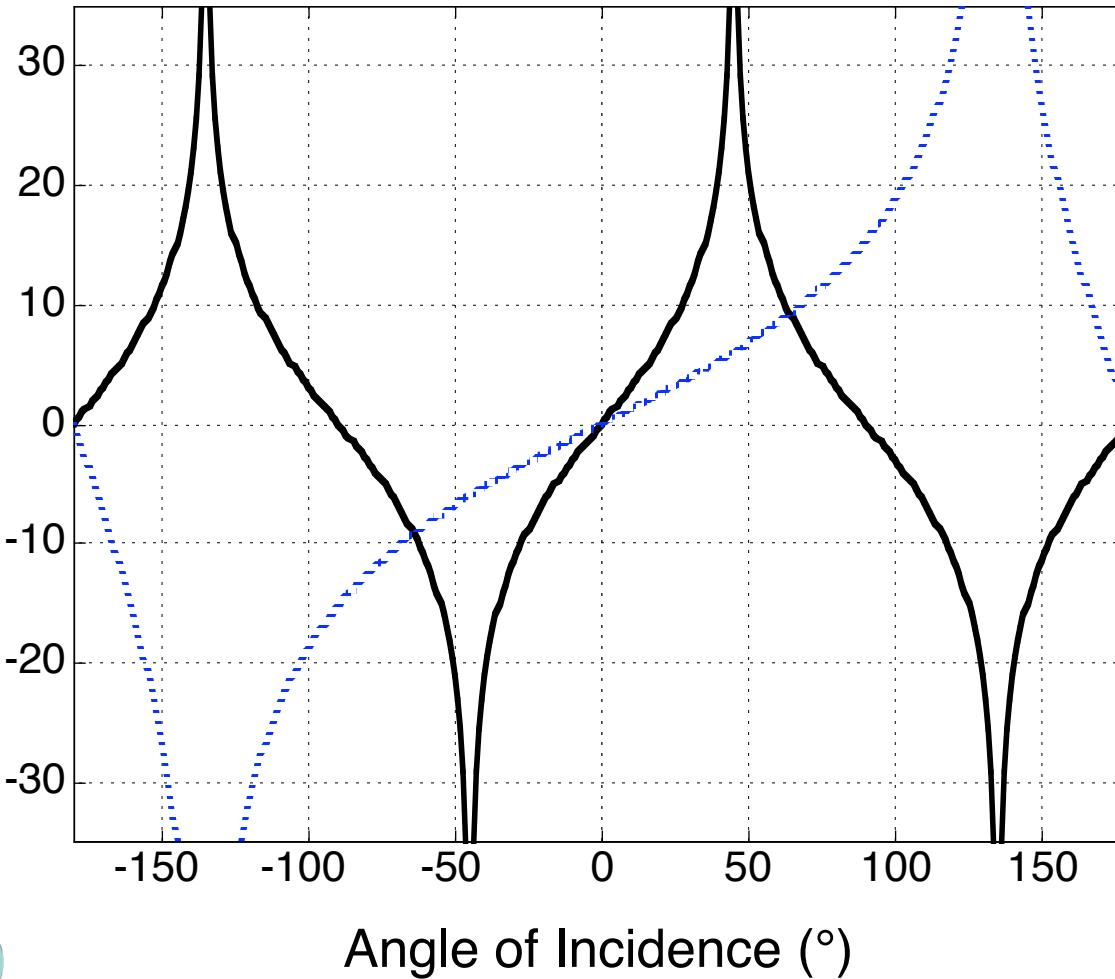
90° Cardioids - Sensitivity Difference



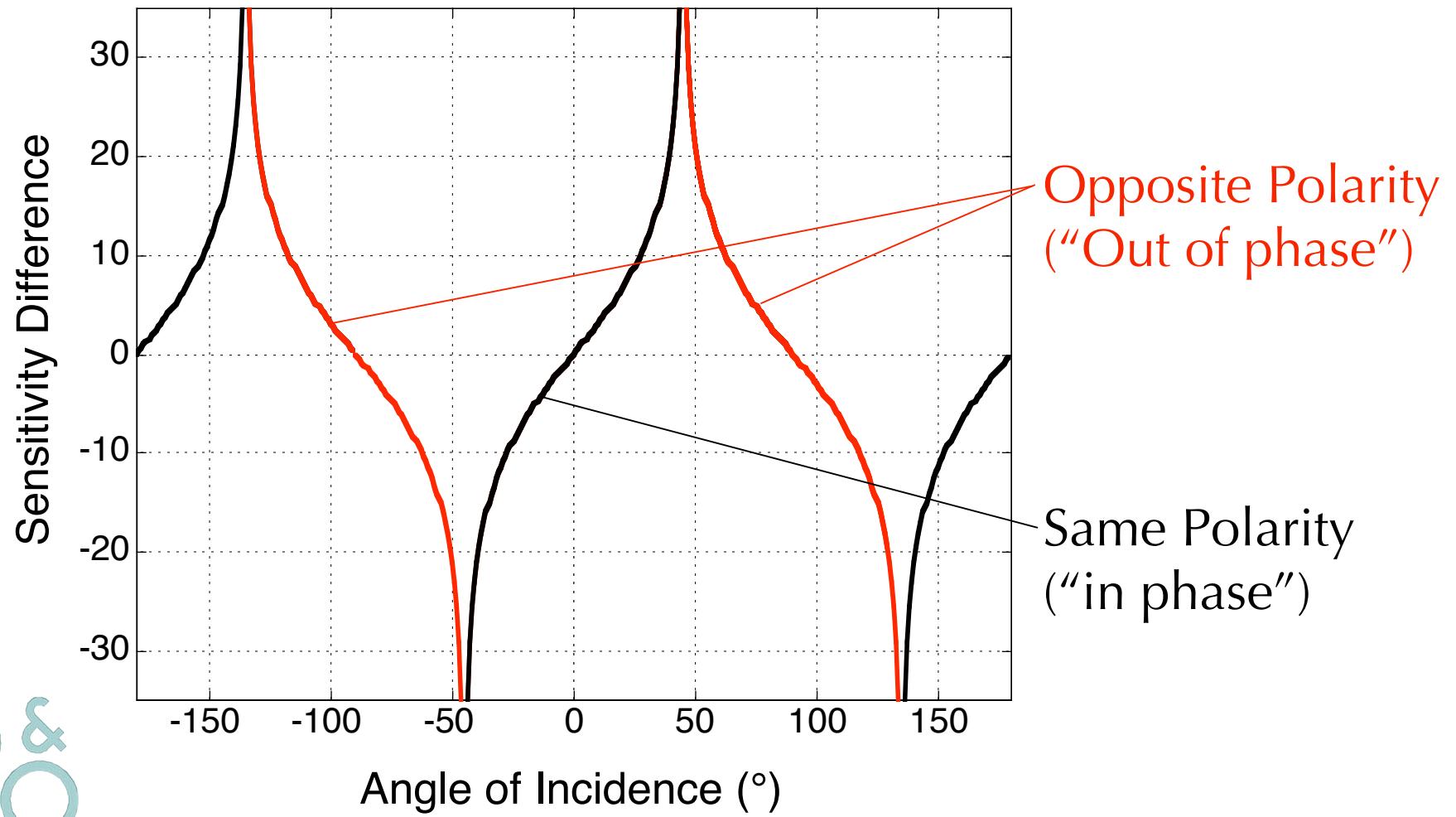
B&O

90° Bidirectionals - Sensitivity Difference

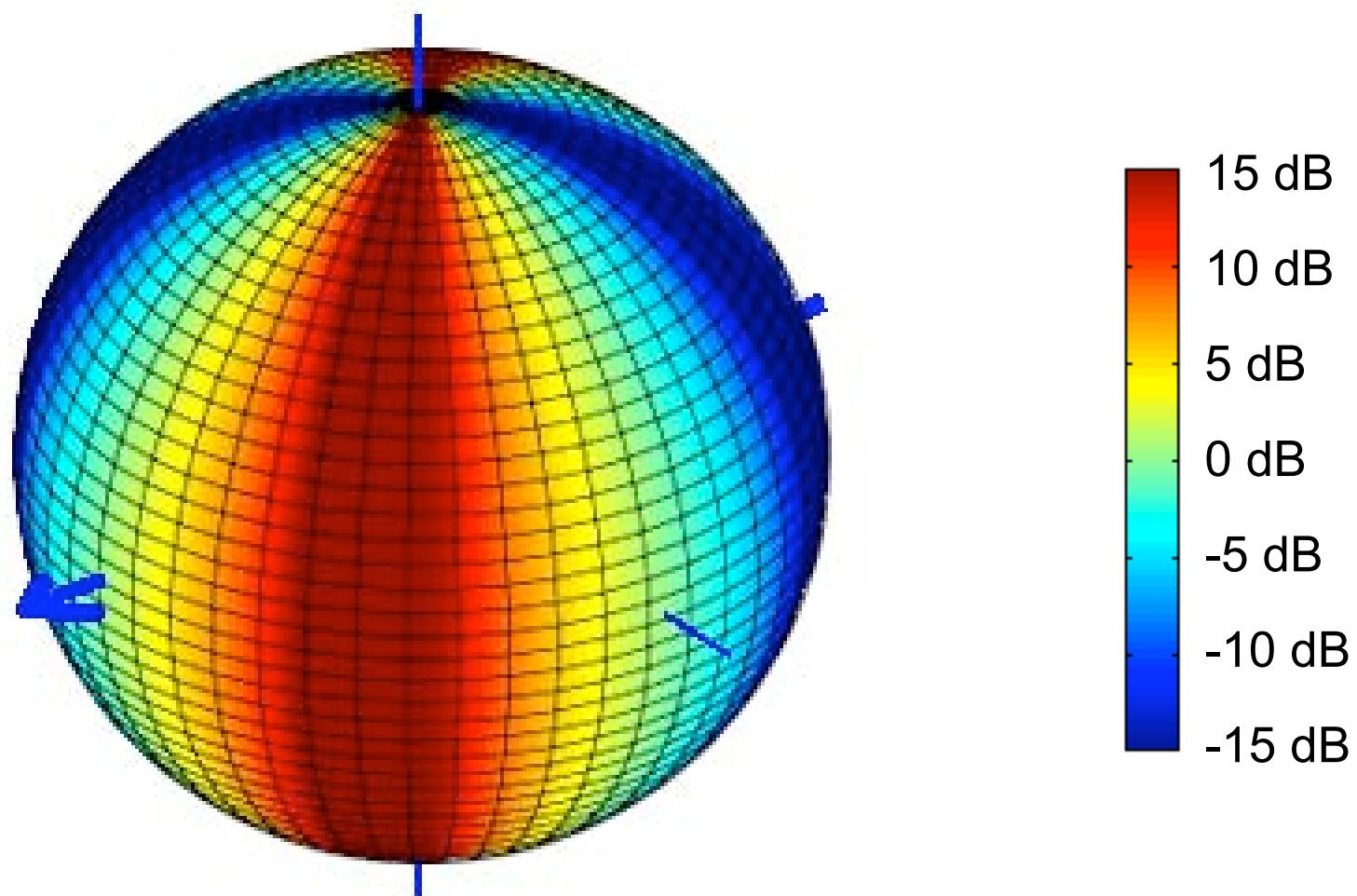
Sensitivity Difference



90° Bidirectionals - Sensitivity Difference

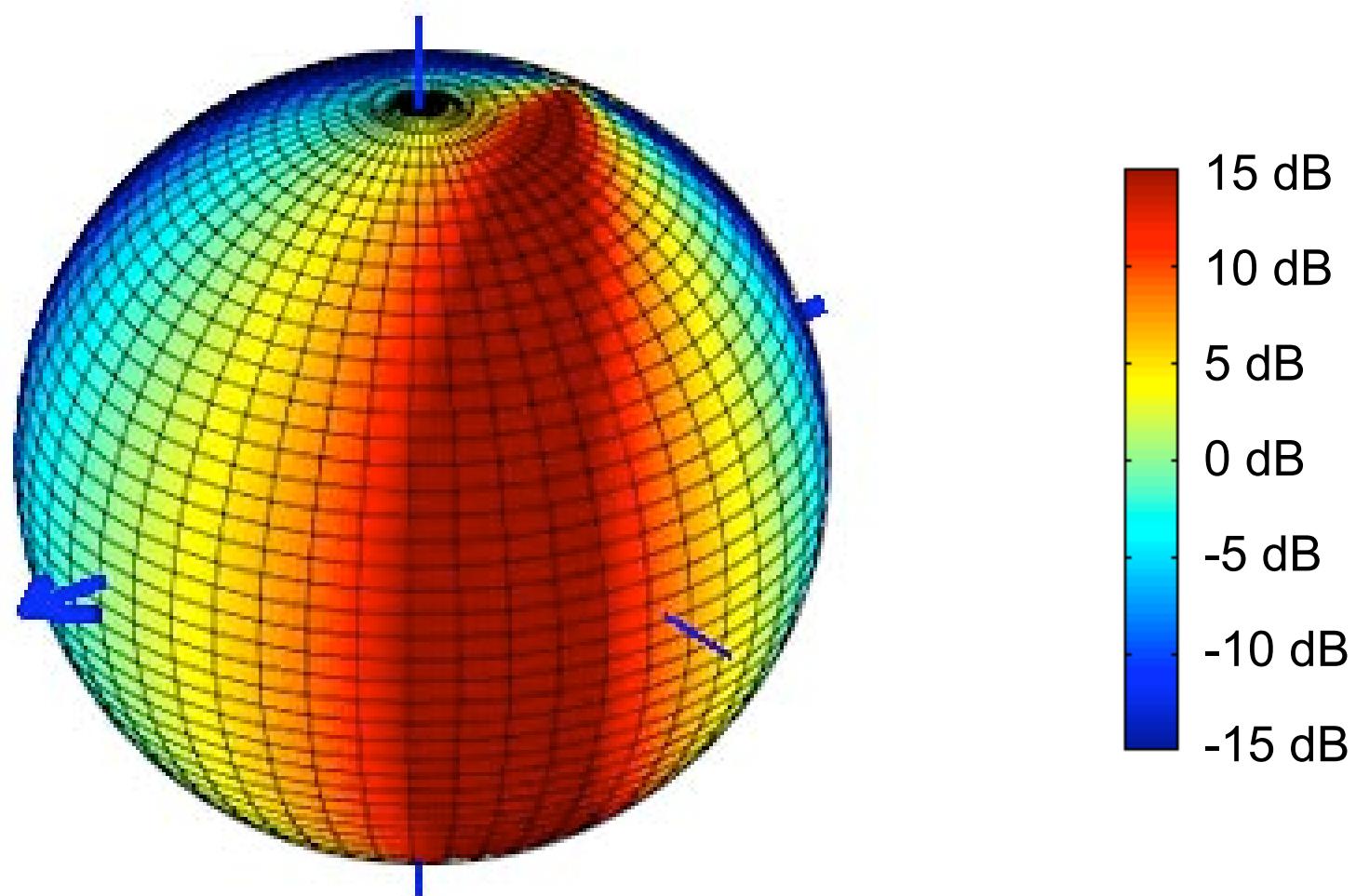


90° Bidirectionals - Sensitivity Difference



B&O

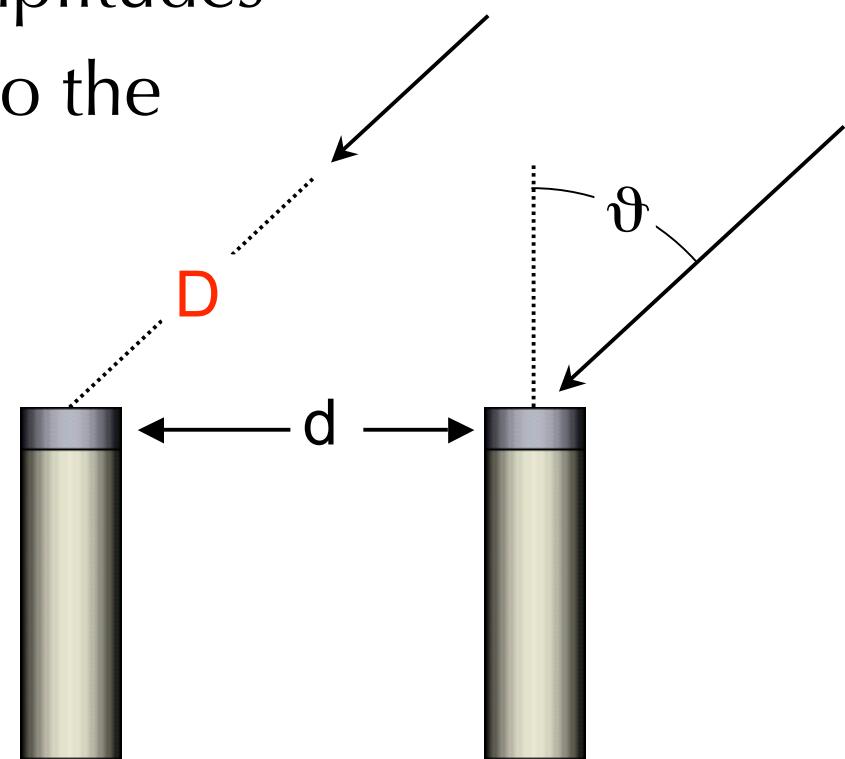
90° Hypercardioids - Sensitivity Difference



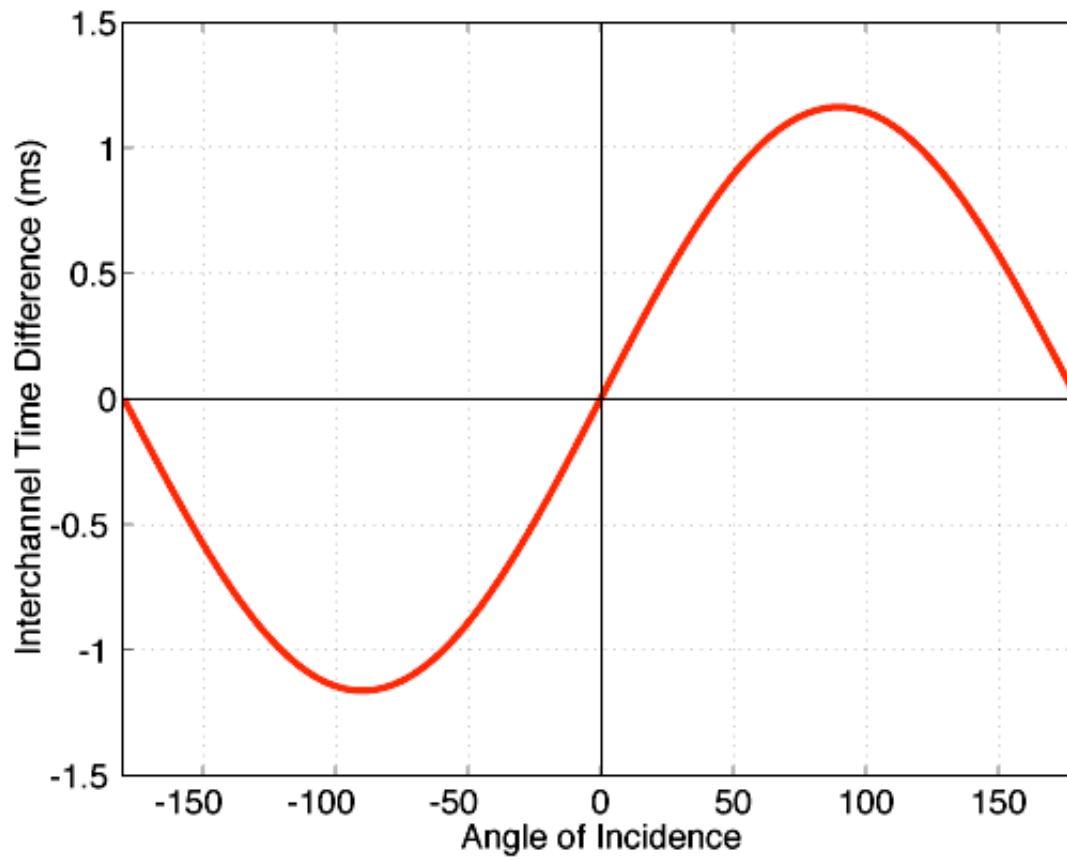
B&O

Spaced Omnidirectionals - Time Difference

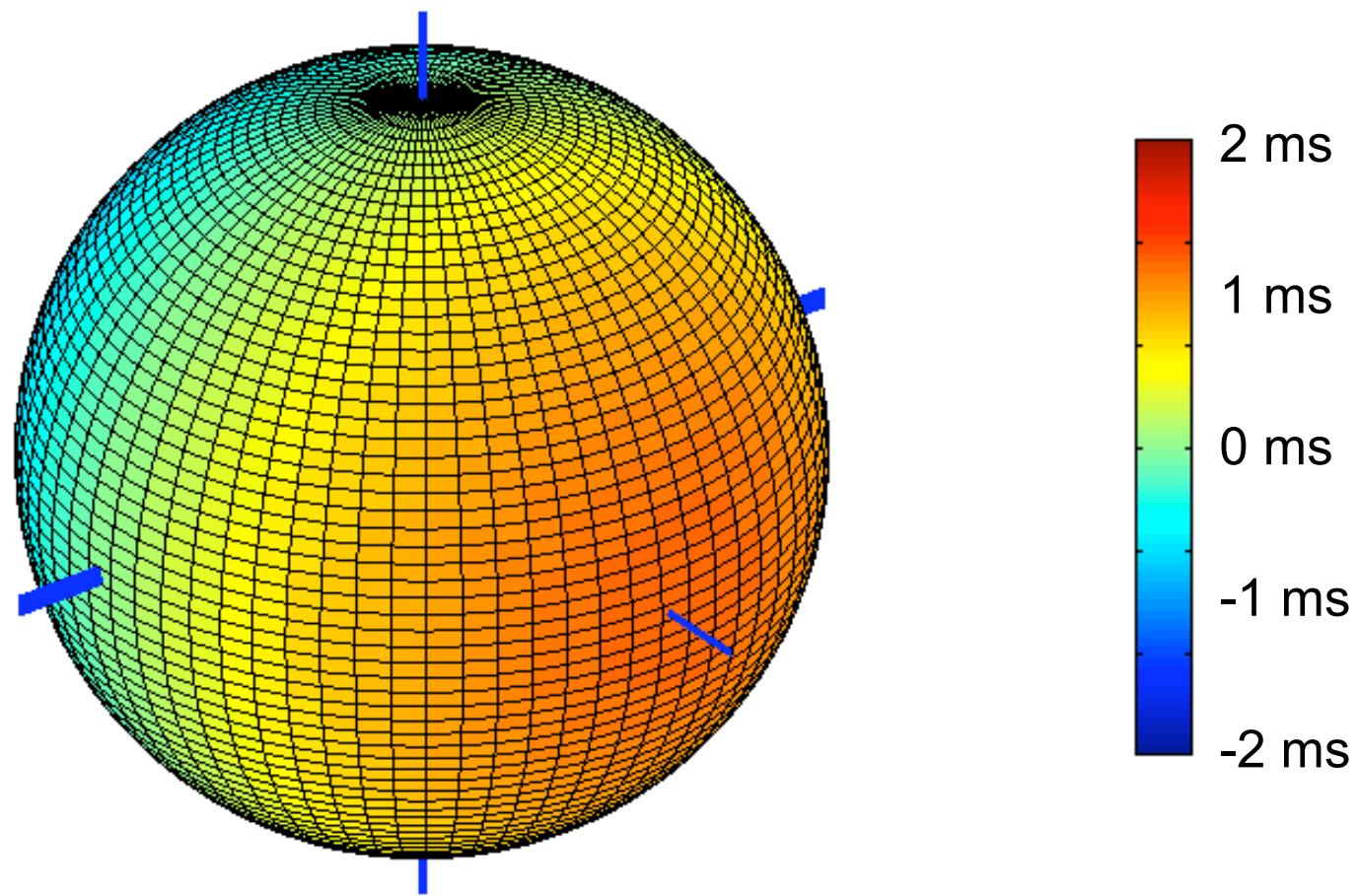
- We assume identical amplitudes
- Differences in distance to the source produce interchannel time difference
- $D = d \sin \vartheta$
- $\Delta T = D / c$



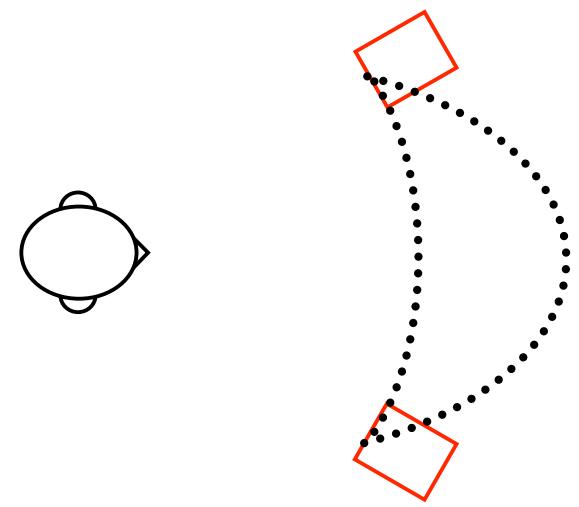
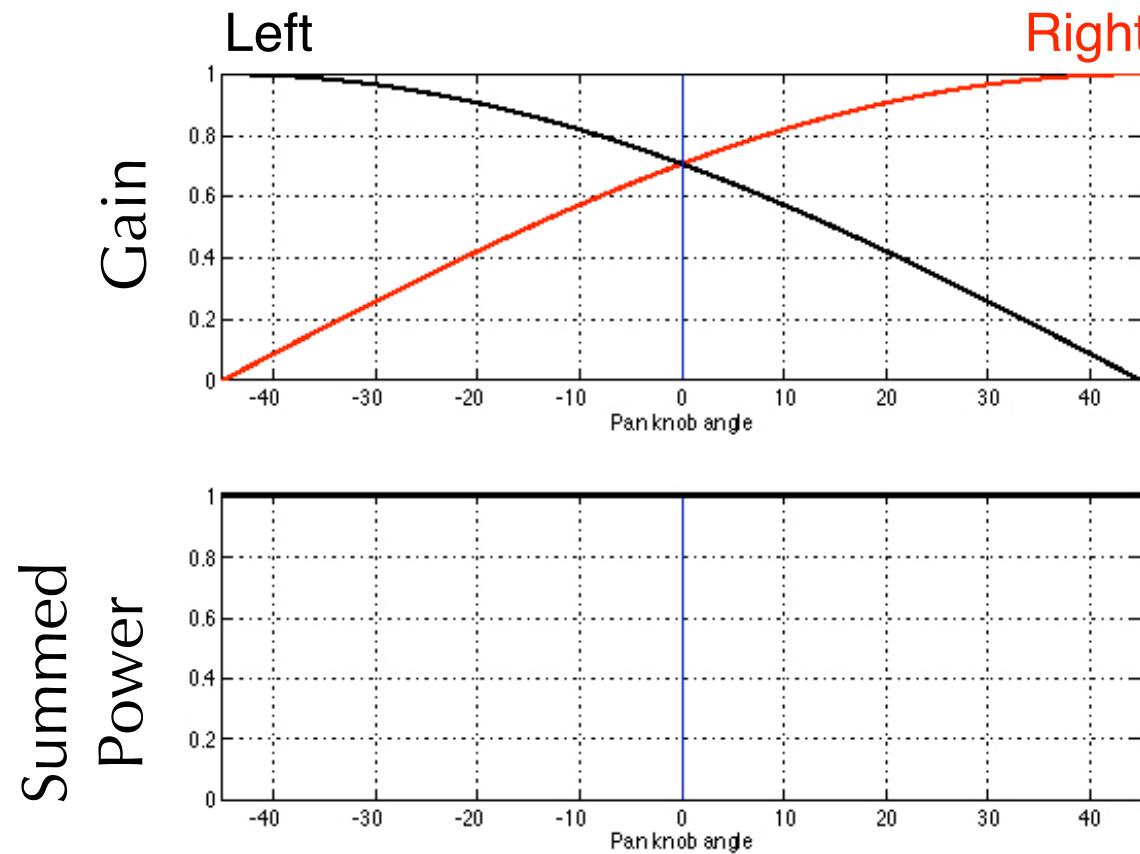
Time difference for 40 cm spacing



Time difference for 40 cm spacing



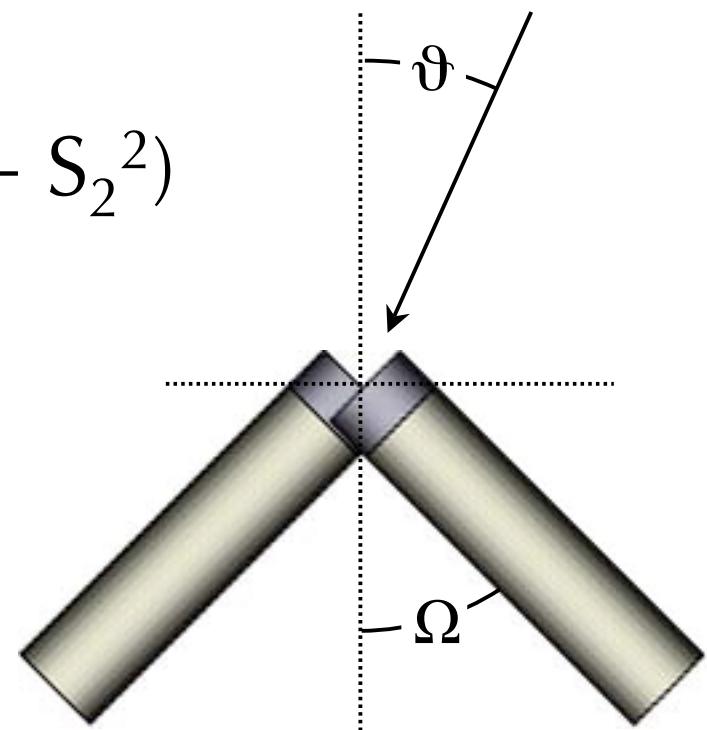
Panning



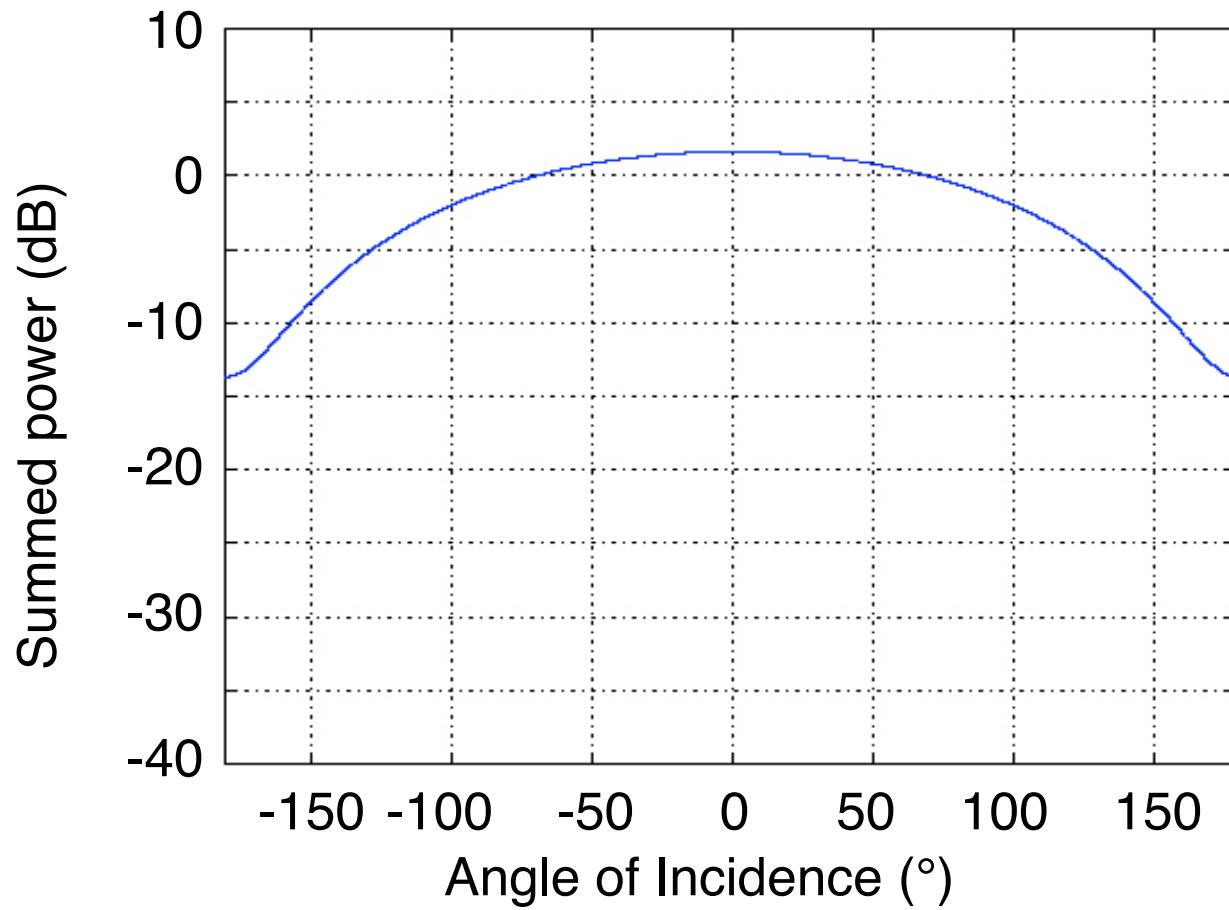
Coincident Microphones - Power Sum

$$S_n = P_n + G_n \cos (\vartheta + \Omega_n)$$

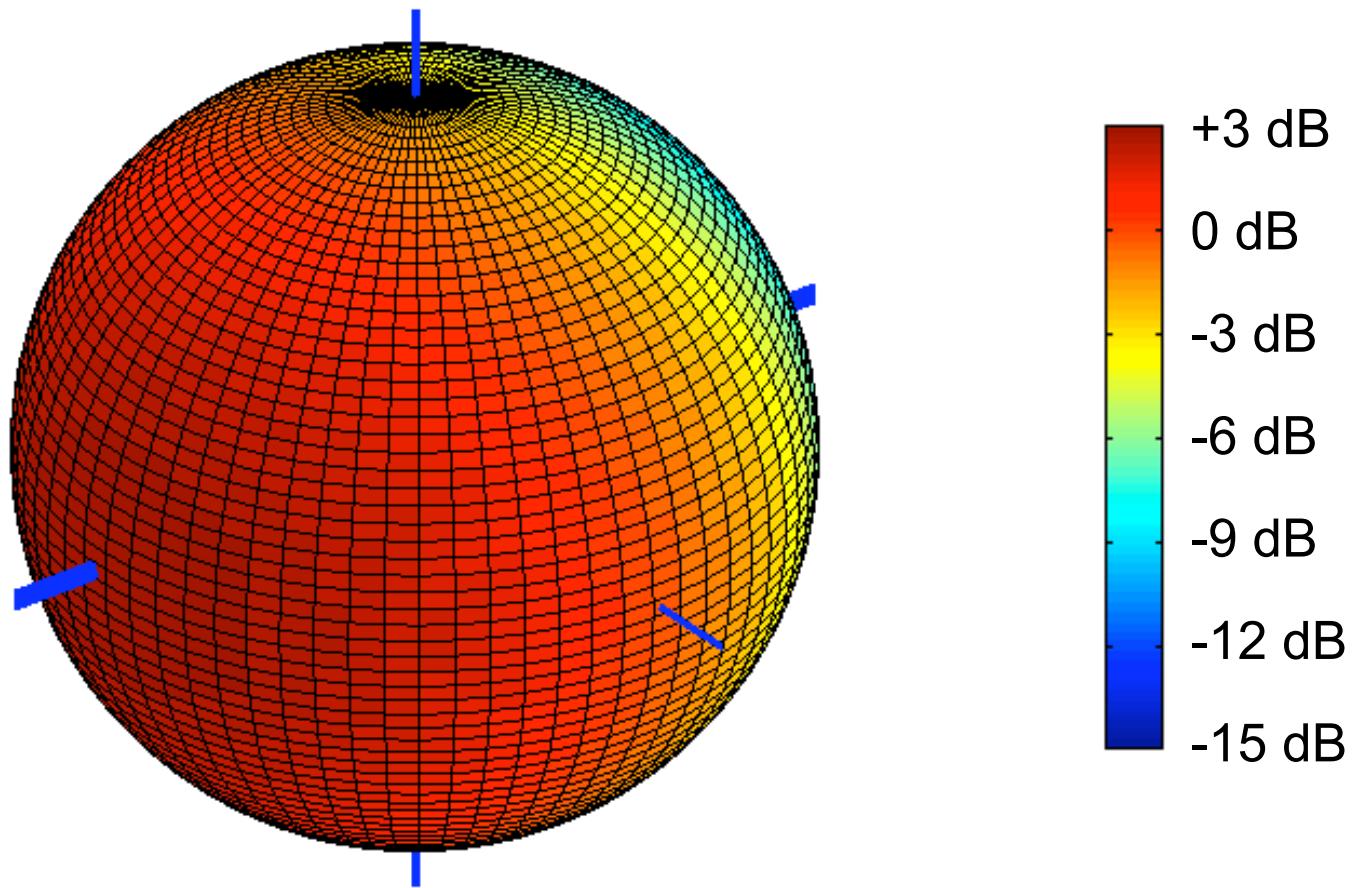
$$S\ Power = 10 \log_{10} (S_1^2 + S_2^2)$$



90° Cardioids - Power Sum

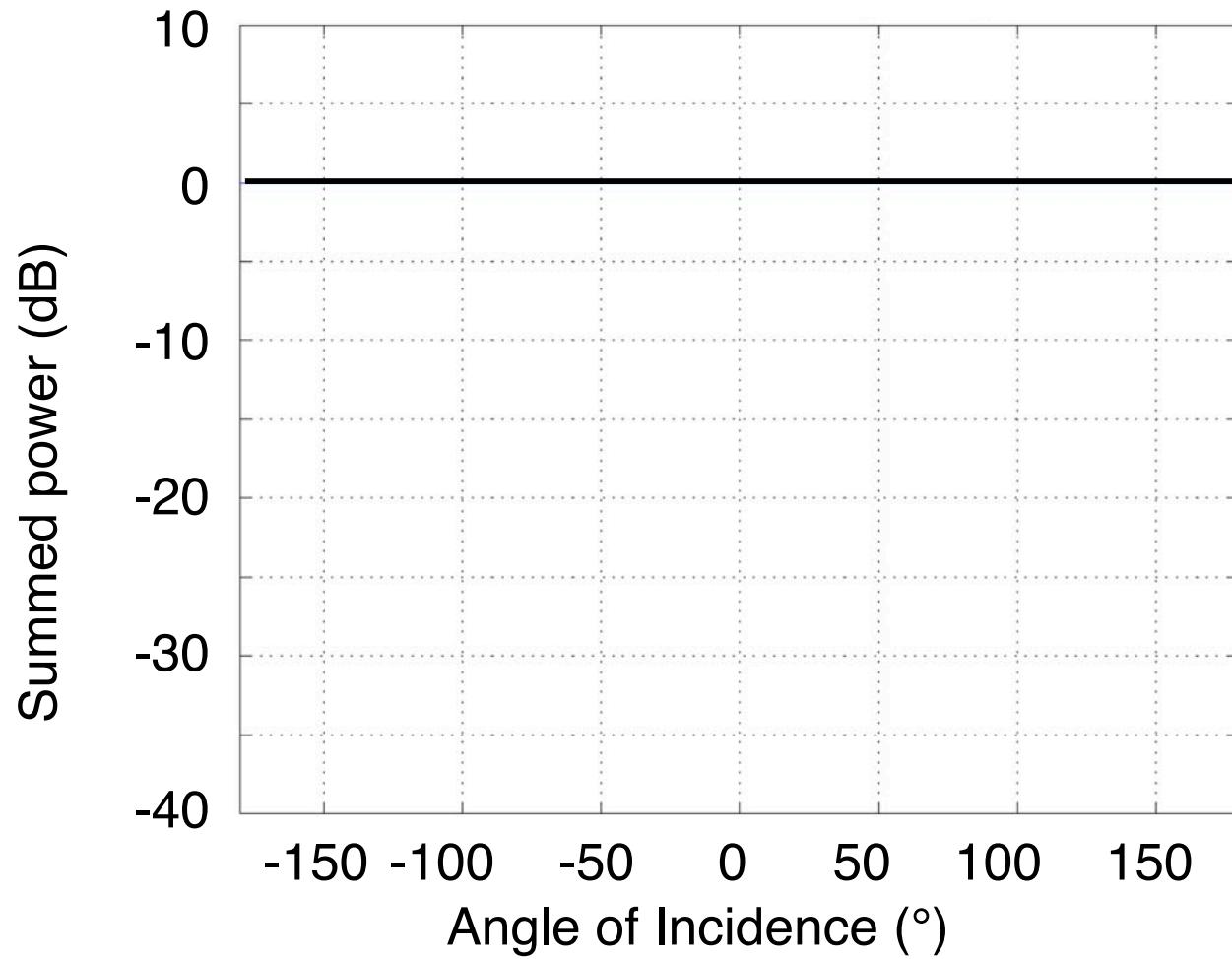


90° Cardioids - Power Sum

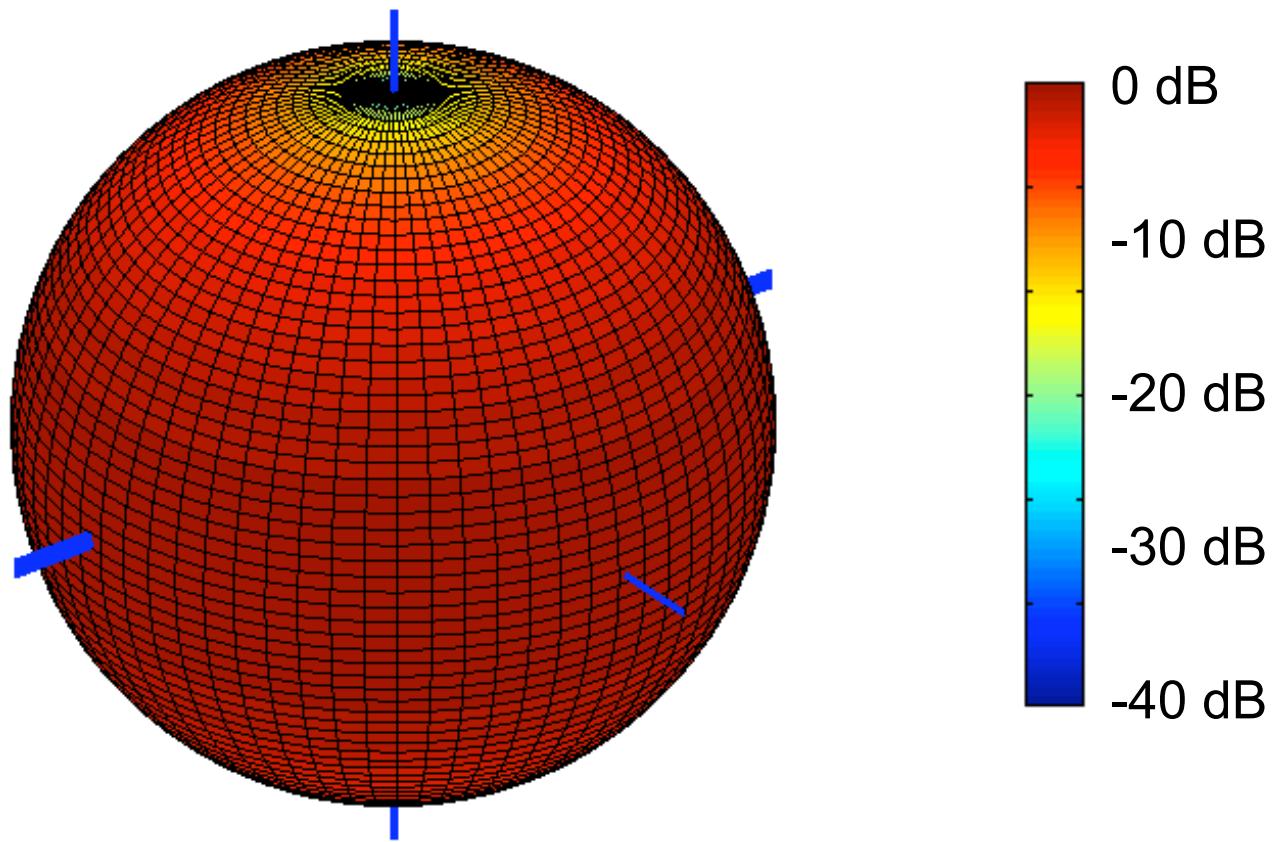


B&O

90° Bidirectionals - Power Sum



90° Cardioids - Power Sum



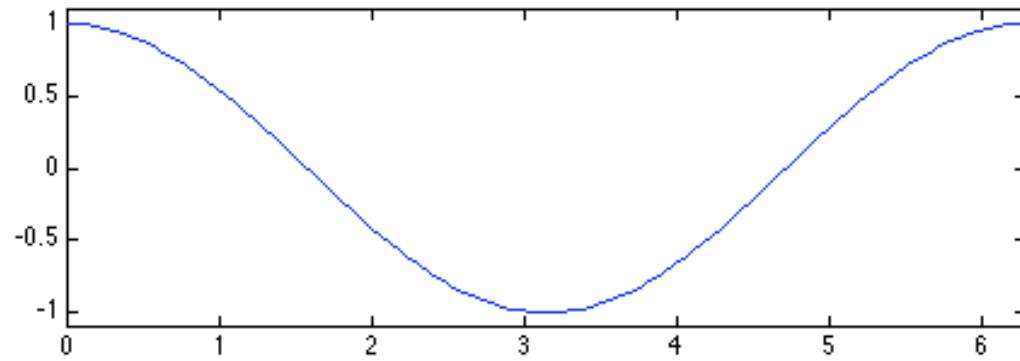
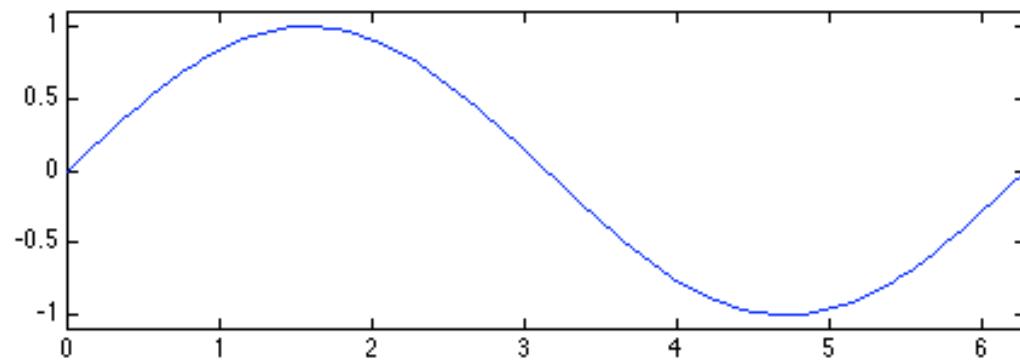
B&O

Correlation Coefficient

- An indicator of the relationship between two signals
- Positive correlation: if one goes up, so does the other
- Negative Correlation: If one goes up, the other goes down
- Correlation = 0: if one goes up, we don't know what the other will do
- Geeky definition: the covariance divided by the product of the standard deviations



Correlation Coefficient



Correlation coefficient

Coincident directional mics, direct sound

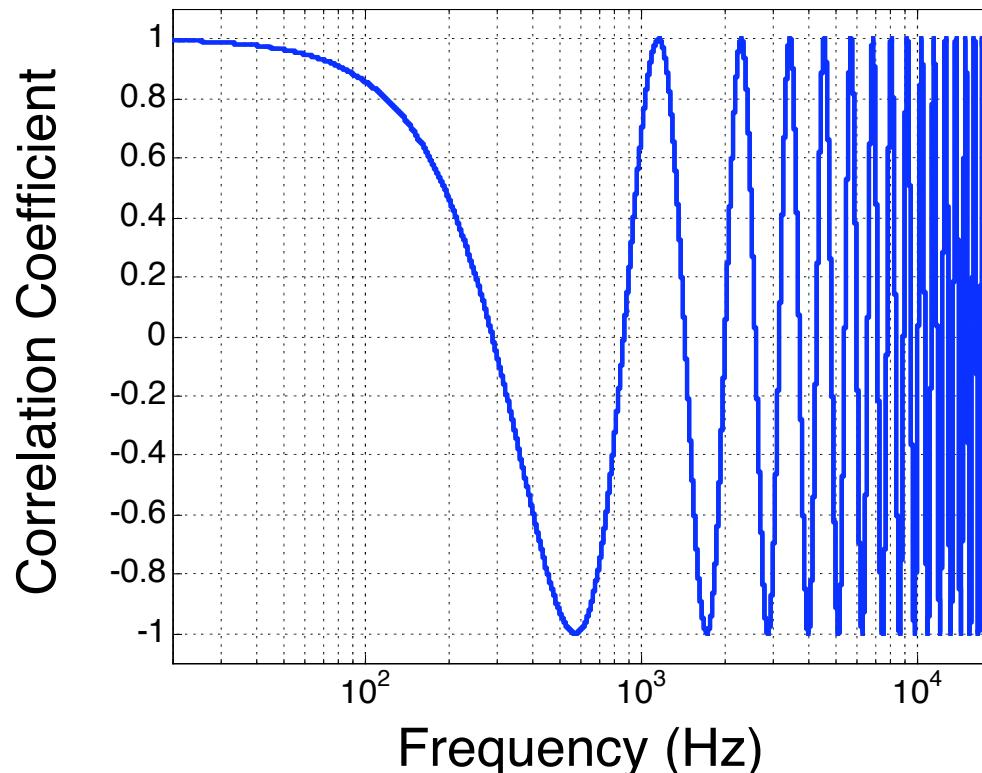
- Coincident mic's have identical time of arrival
- Only differences are:
 - Amplitude
 - Polarity
- Correlation coefficient must be either 1, 0 or -1



Correlation coefficient

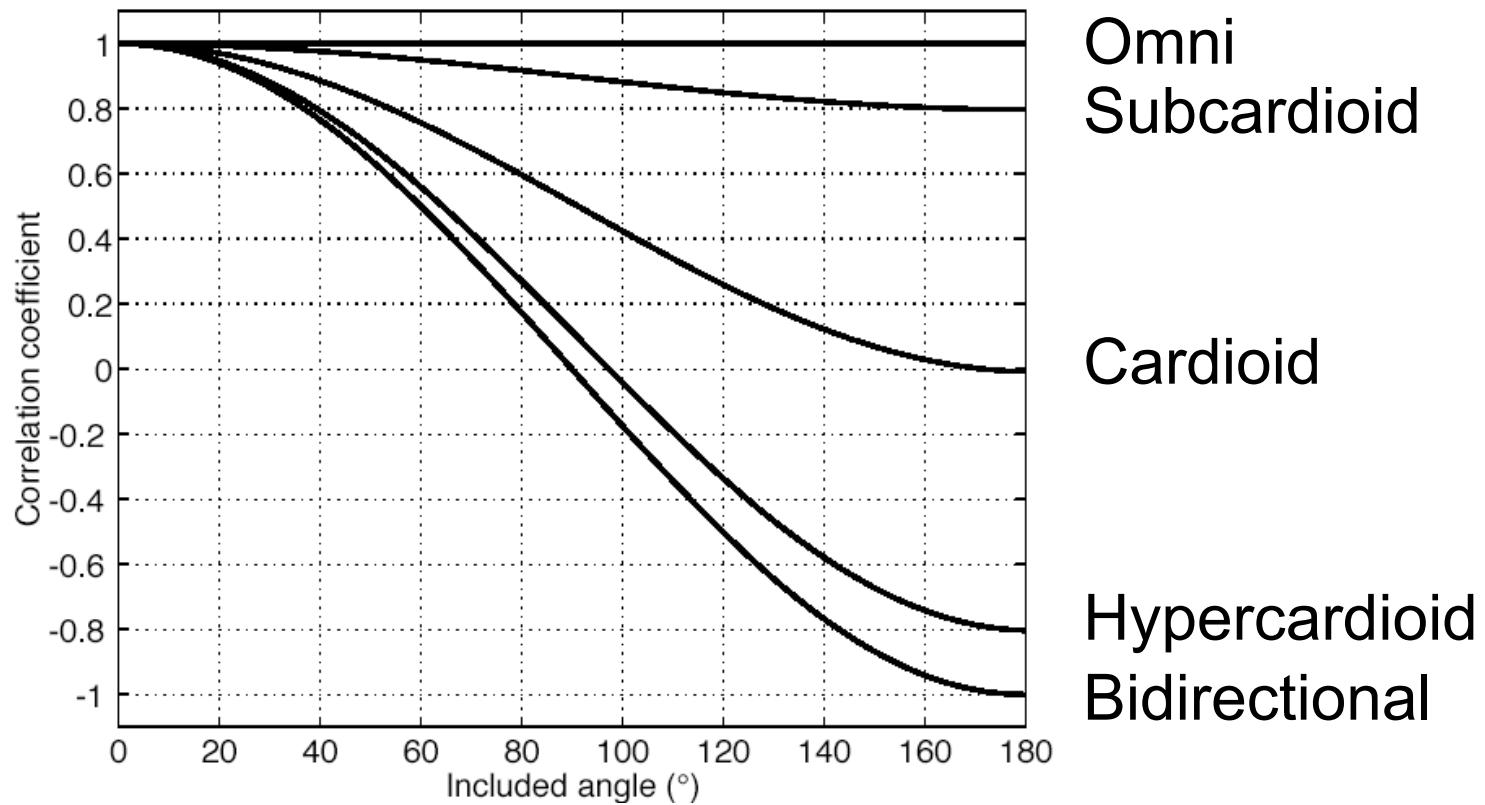
Spaced mics, direct sound

- Spaced mic's have different times of arrival
- This results in a phase difference

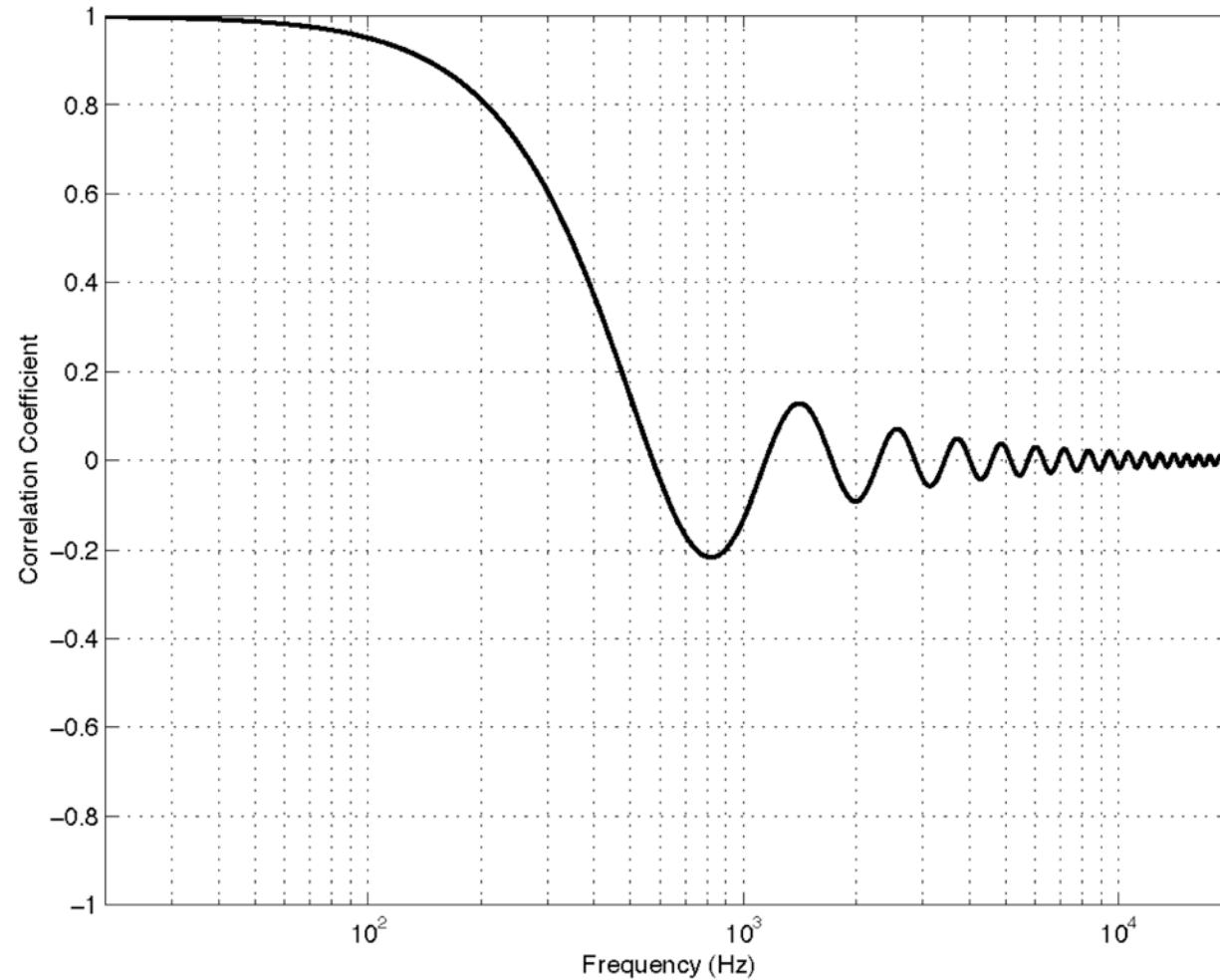


Correlation coefficient

Coincident directional, diffuse field



Correlation coefficient 30 cm spaced omni's in a diffuse field

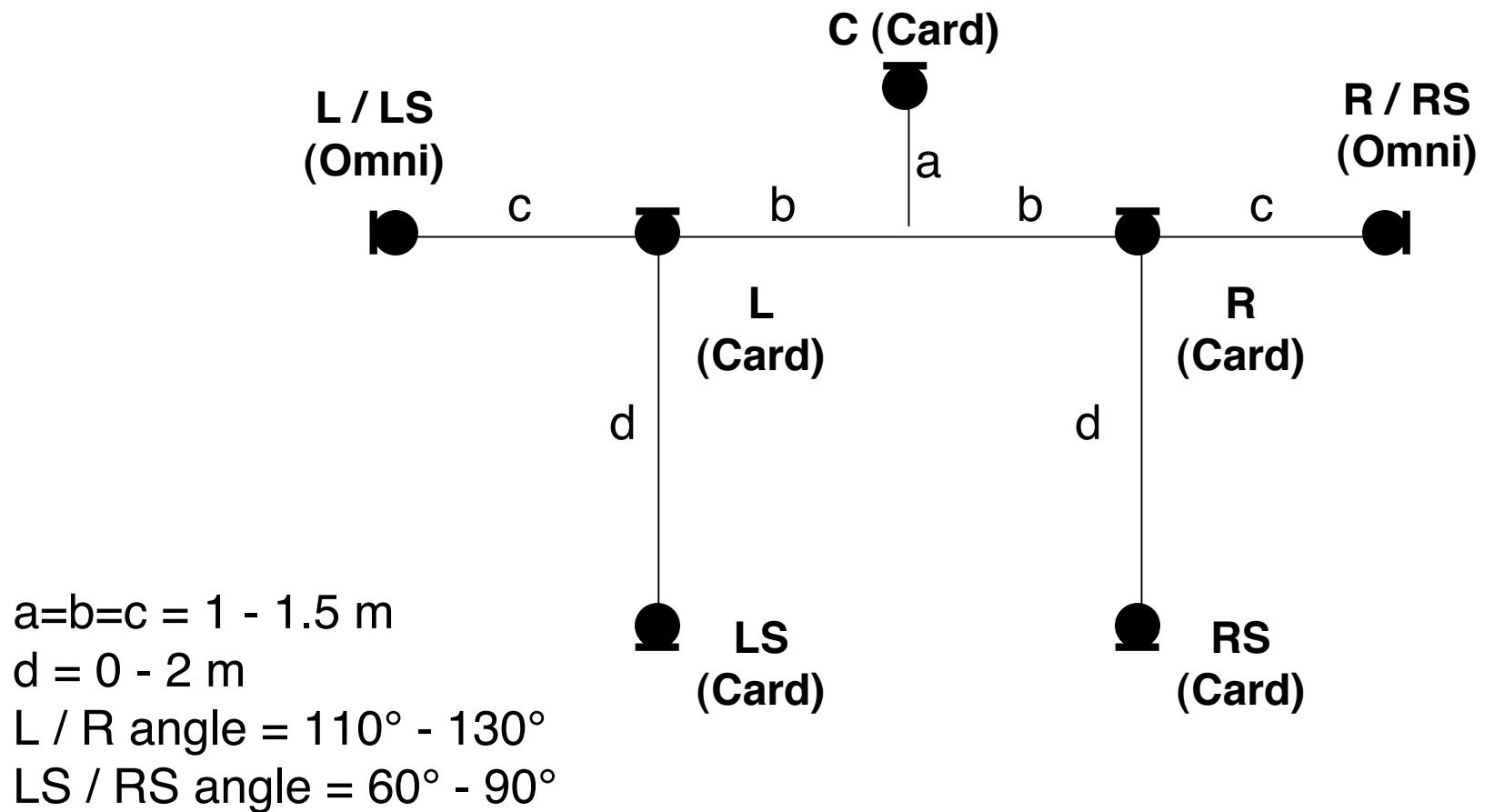


Conclusions

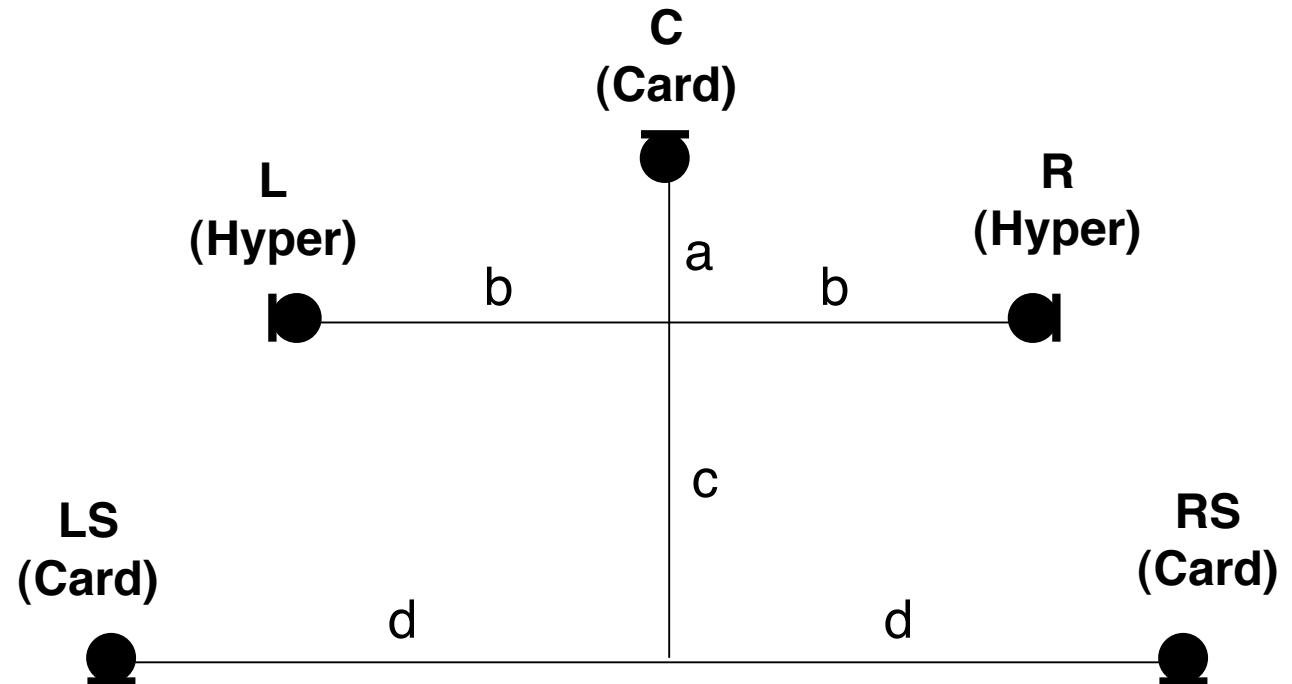
- Every recording situation requires a different microphone configuration
- Treat “standard” or “textbook” configurations only as suggestions
- Understand the behaviour of the microphones and their configuration but...
- Trust your ears!
- www.tonmeister.ca/research
- www.hauptmikrofon.de
- Michael Williams's AES papers



Fukada Tree



OCT Surround



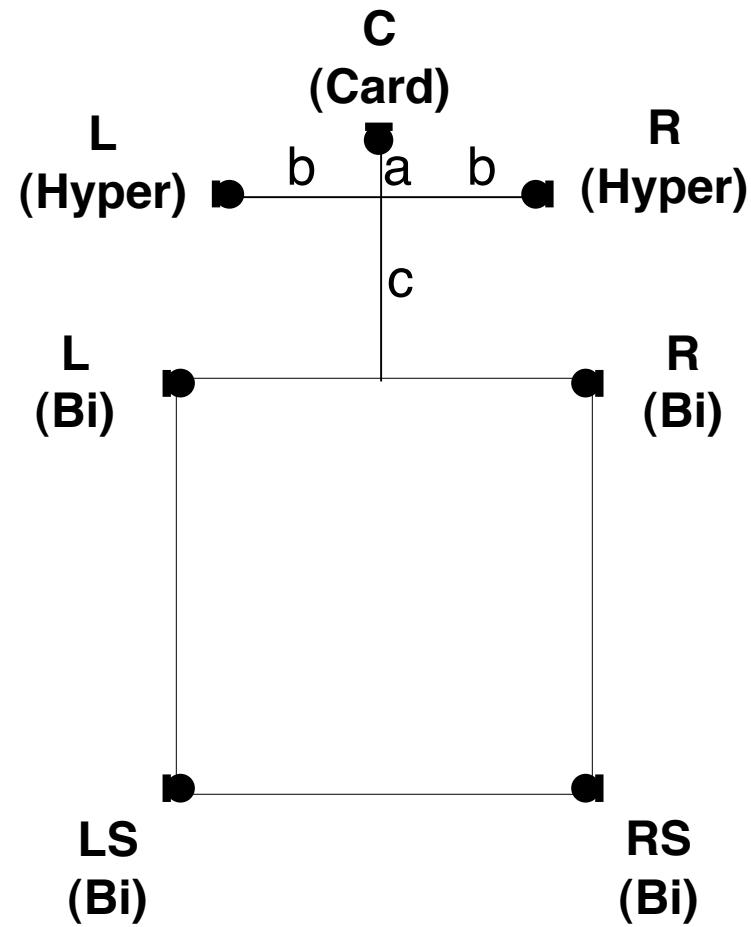
$a = 8 \text{ cm}$

$b = 40 - 90 \text{ cm}$

$c = 40 \text{ cm}$

$d = 10 - 100 \text{ cm}$

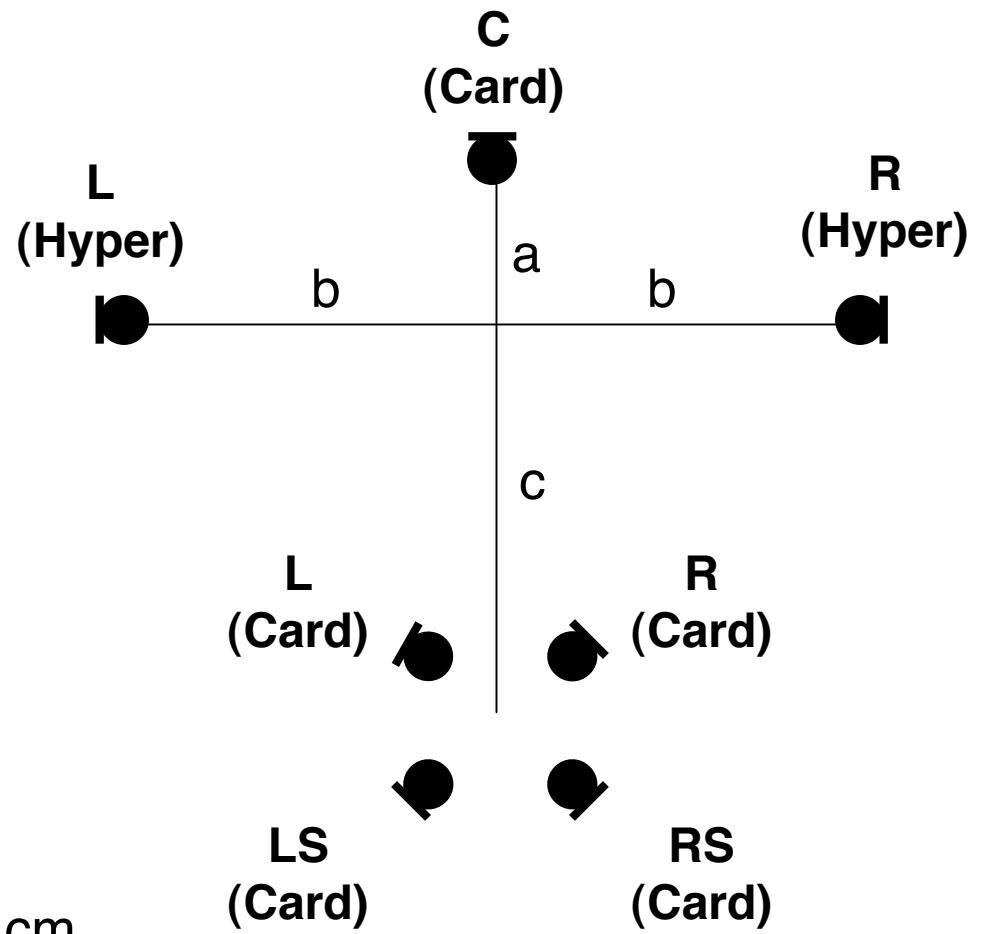
OCT Frontsystem + Hamasaki Square



a = 8 cm
b = 40 - 90 cm
c = ~100 cm
Cross side = 2 - 3 m



OCT Frontsystem + IRT Cross



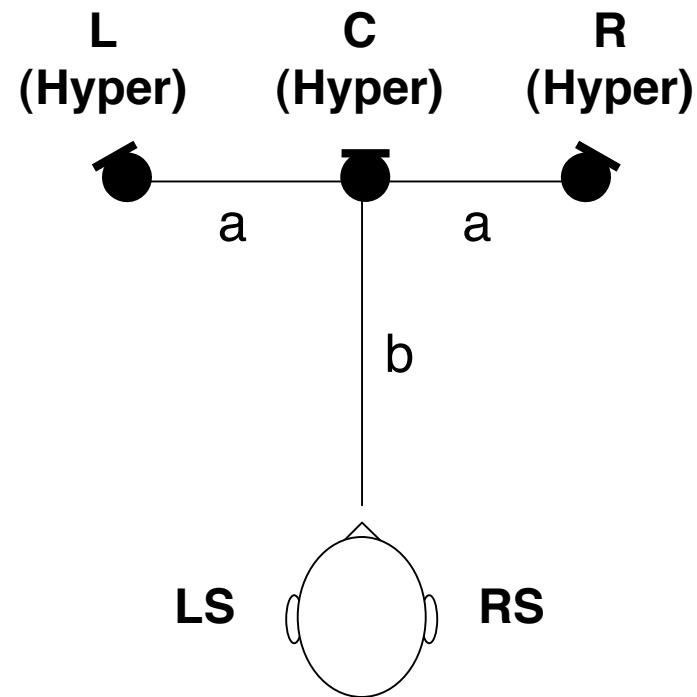
a = 8 cm

b = 40 - 90 cm

c = ~100 cm

Cross side = 20 - 25 cm

Klepko Technique

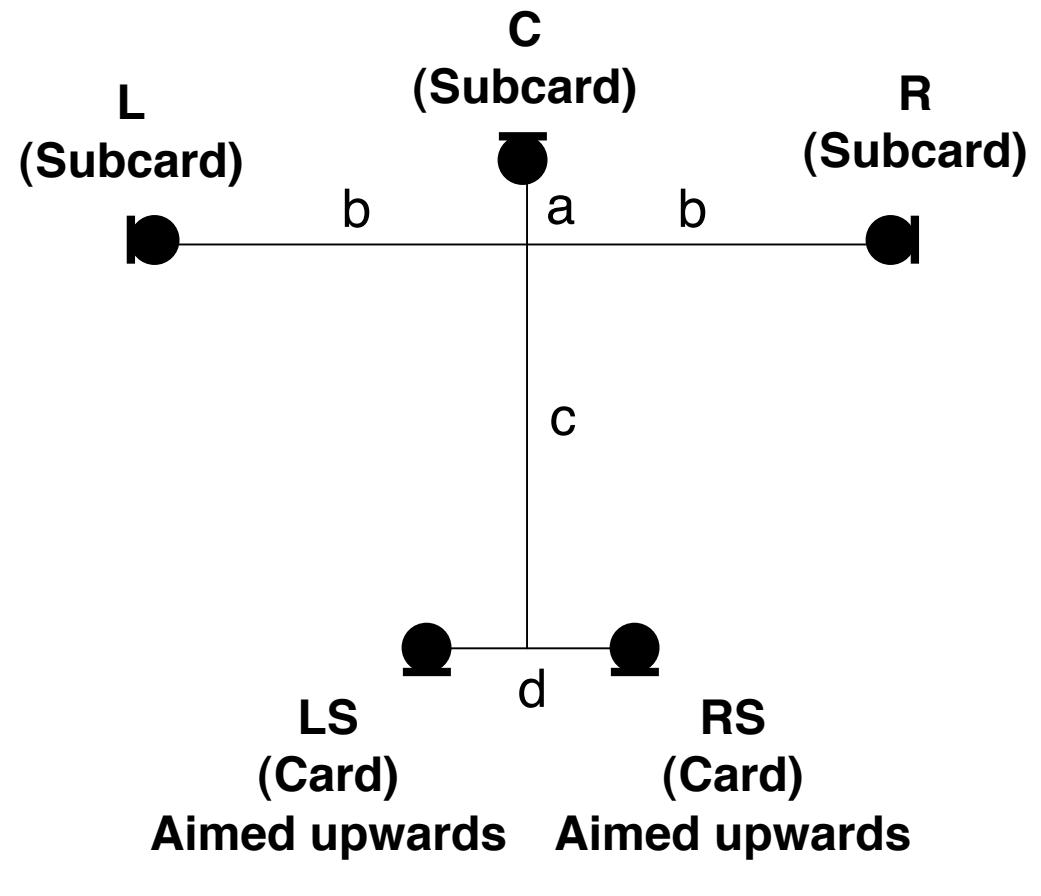


$a = 17.5 \text{ cm}$

$b = 125 \text{ cm}$

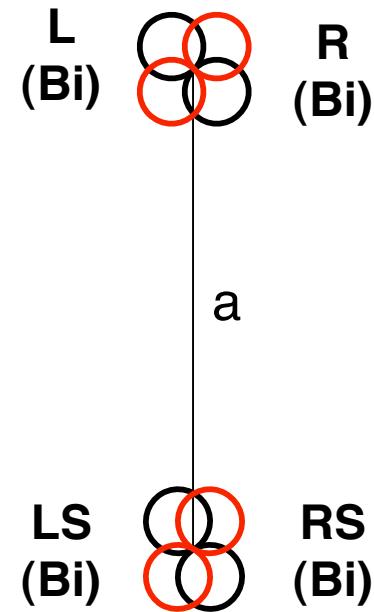
L/R Angle $\pm 30^\circ$

Corey / Martin Tree



Martin Tree

C
(Bi - pointing downwards)



$a = < 70 \text{ cm}$
LS/RS angle = $45^\circ - 90^\circ$

